3.3 Analysis of Members under Flexure (Part II)

This section covers the following topics.

- Cracking Moment
- Kern Points
- Pressure Line

Introduction

The analysis of flexural members under service loads involves the calculation of the following quantities.

- a) Cracking moment.
- b) Location of kern points.
- c) Location of pressure line.

The following material explains each one of them.

3.2.1 Cracking Moment

The cracking moment (M_{cr}) is defined as the moment due to external loads at which the first crack occurs in a prestressed flexural member. Considering the variability in stress at the occurrence of the first crack, the evaluated cracking moment is an estimate. Nevertheless, the evaluation of cracking moment is important in the analysis of prestressed members.

Based on the allowable tensile stress the prestress members are classified into three types as per **IS:1343 - 1980**. The types are explained in Section 1.2, Advantages and Types of Prestressing. For Type 1 (full prestressing) and Type 2 (limited prestressing) members, cracking is not allowed under service loads. Hence, it is imperative to check that the cracking moment is greater than the moment due to service loads. This is satisfied when the stress at the edge due to service loads is less than the modulus of rupture.

The **modulus of rupture** is the stress at the bottom edge of a simply supported beam corresponding to the cracking moment (M_{cr}). The modulus of rupture is a measure of the flexural tensile strength of concrete. It is measured by testing beams under 2 point

loading (also called 4 point loading including the reactions or middle third loading). The modulus of rupture (f_{cr}) is expressed in terms of the characteristic compressive strength (f_{ck}) of concrete by the following equation (**IS:456 - 2000**). Here, f_{cr} and f_{ck} are in N/mm².

$$f_{cr} = 0.7\sqrt{f_{ck}}$$
 (3-3.1)

The following sketch shows the internal forces and the resultant stress profile at the instant of cracking.

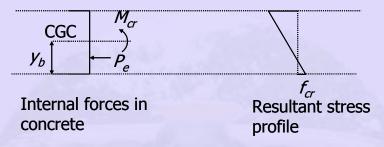


Figure 3-3.1 Internal forces and resultant stress profile at cracking

The stress at the edge can be calculated based on the stress concept as follows. The cracking moment (M_{cr}) can be evaluated by transposing the terms.

$$\frac{P_e}{A} - \frac{P_e e y_b}{I} + \frac{M_{cr} y_b}{I} = f_{cr}$$
or,
$$\frac{M_{cr} y_b}{I} = f_{cr} + \frac{P_e}{A} + \frac{P_e e y_b}{I}$$
or,
$$M_{cr} = \frac{f_{cr} I}{y_b} + \frac{P_e I}{A y_b} + P_e e$$
(3-3.2)

The above equation expresses M_{cr} in terms of the section and material properties and prestressing variables.

3.2.2 Kern Points

When the resultant compression (*C*) is located within a specific zone of a section of a beam, tensile stresses are not generated. This zone is called the kern zone of a section. For a section symmetric about a vertical axis, the kern zone is within the levels of the upper and lower kern points. When the resultant compression (C) under service loads is located at the upper kern point, the stress at the bottom edge is zero. Similarly, when *C* at transfer of prestress is located at the upper

edge is zero. The levels of the upper and lower kern points from CGC are denoted as k_t and k_b , respectively.

Based on the stress concept, the stress at the bottom edge corresponding to C at the upper kern point, is equated to zero. The following sketch shows the location of C and the resultant stress profile.

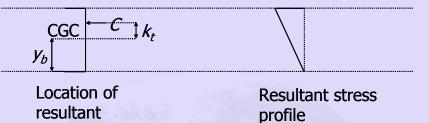


Figure 3-3.2 Resultant stress profile when compression is at upper kern point

compression

The value of k_t can be calculated by equating the stress at the bottom to zero as follows.

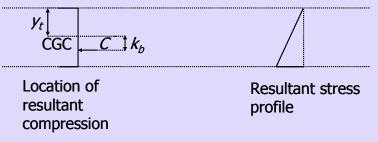
$$-\frac{C}{A} + \frac{Ck_t y_b}{I} = 0$$

or,
$$-\frac{C}{A} + \frac{Ck_t y_b}{Ar^2} = 0$$

or,
$$k_t = \frac{r^2}{y_b}$$
 (3-3.3)

The above equation expresses the location of upper kern point in terms of the section properties. Here, *r* is the radius of gyration and y_b is the distance of the bottom edge from CGC.

Similar to the calculation of k_t , the location of the bottom kern point can be calculated by equating the stress at the top edge to zero. The following sketch shows the location of *C* and the resultant stress profile.





$$-\frac{C}{A} + \frac{Ck_b y_t}{I} = 0$$

or,
$$-\frac{C}{A} + \frac{Ck_b y_t}{Ar^2} = 0$$

or,
$$k_b = \frac{r^2}{y_t}$$
 (3-3.4)

Here, y_t is the distance of the top edge from CGC.

Cracking Moment using Kern Points

The kern points can be used to determine the cracking moment (M_{cr}). The cracking moment is slightly greater than the moment causing zero stress at the bottom. *C* is located above k_t to cause a tensile stress f_{cr} at the bottom. The incremental moment is $f_{cr} I/y_b$. The following sketch shows the shift in *C* outside the kern to cause cracking and the corresponding stress profiles.

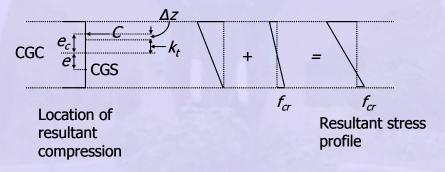


Figure 3-3.4 Resultant stress profile at cracking of the bottom edge

The cracking moment can be expressed as the product of the compression and the lever arm. The lever arm is the sum of the eccentricity of the CGS (*e*) and the eccentricity of the compression (*e_c*). The later is the sum of k_t and Δz , the shift of *C* outside the kern.

$$M_{cr} = C(e + e_c)$$

= $C(e + k_t + \Delta z)$
or, $M_{cr} = C(e + k_t) + \frac{f_{cr}I}{y_b}$ (3-3.5)

Substituting $C = P_e$, $k_t = r^2/y_b$ and $r^2 = I/A$, the above equation becomes same as the previous expression of M_{cr} .

$$M_{cr} = P_e \left(\frac{r^2}{y_b} + e \right) + \frac{f_{cr}I}{y_b}$$

or, $M_{cr} = \frac{f_{cr}I}{y_b} + \frac{P_eI}{Ay_b} + P_e e$ (3-3.6)

3.2.3 Pressure Line

The pressure line in a beam is the locus of the resultant compression (*C*) along the length. It is also called the **thrust line** or **C-line**. It is used to check whether *C* at transfer and under service loads is falling within the kern zone of the section. The eccentricity of the pressure line (e_c) from CGC should be less than k_b or k_t to ensure *C* in the kern zone.

The pressure line can be located from the lever arm (*z*) and eccentricity of CGS (*e*) as follows. The lever arm is the distance by which C shifts away from *T* due to the moment. Subtracting *e* from *z* provides the eccentricity of *C* (e_c) with respect to CGC. The variation of e_c along length of the beam provides the pressure line.

$$z = \frac{M}{C}$$

 $\varphi_c = z - e$ (3-3.7)

A positive value of e_c implies that C acts above the CGC and vice-versa. If e_c is negative and the numerical value is greater than k_b (that is $|e_c| > k_b$), C lies below the lower kern point and tension is generated at the top of the member. If $e_c > k_t$, then C lies above the upper kern point and tension is generated at the bottom of the member.

Pressure Line at Transfer

The pressure line is calculated from the moment due to the self weight. The following sketch shows that the pressure line for a simply supported beam gets shifted from the CGS with increasing moment towards the centre of the span.

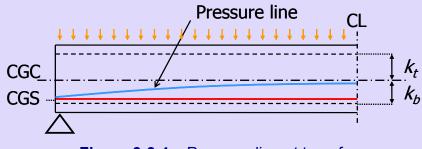
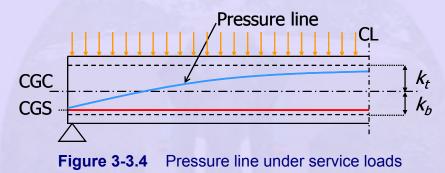


Figure 3-3.4 Pressure line at transfer

Pressure Line under Service Loads

The pressure line is calculated from the moment due to the service loads. The following sketch shows that the pressure line for a simply supported beam gets further shifted from the CGS at the centre of the span with increased moment under service condition.



Limiting Zone

For fully prestressed members (Type 1), tension is not allowed under service conditions. If tension is also not allowed at transfer, *C* always lies within the kern zone. The limiting zone is defined as the zone for placing the CGS of the tendons such that *C* always lies within the kern zone.

For limited prestressed members (Type 2 and Type 3), tension is allowed at transfer and under service conditions. The limiting zone is defined as the zone for placing the CGS such that the tensile stresses in the extreme edges are within the allowable values.

The following figure shows the limiting zone (as the shaded region) for a simply supported beam subjected to uniformly distributed load.

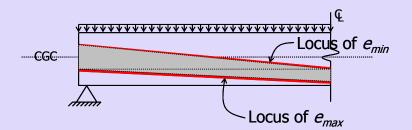
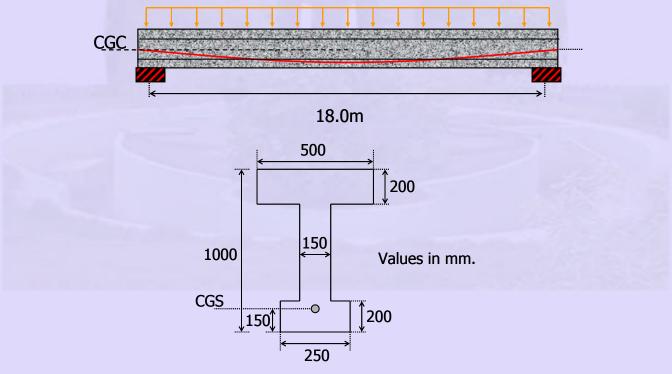


Figure 3-3.4 Limiting zone for a simply supported beam

The determination of limiting zone is given in Section 4.4, Design of Sections for Flexure (Part III).

Example 3-3.1

For the post-tensioned beam with a flanged section as shown, the profile of the CGS is parabolic, with no eccentricity at the ends. The live load moment due to service loads at mid-span (M_{LL}) is 648 kNm. The prestress after transfer (P_0) is 1600 kN. Assume 15% loss at service. Grade of concrete is M30.



Cross-section at mid-span

Evaluate the following quantities.

- a) Kern levels
- b) Cracking moment
- c) Location of pressure line at mid-span at transfer and at service.
- d) The stresses at the top and bottom fibres at transfer and at service.

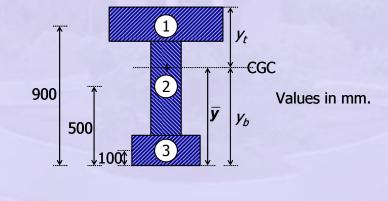
Compare the stresses with the following allowable stresses at transfer and at service.

For compression, $f_{cc,all} = -18.0 \text{ N/mm}^2$ For tension, $f_{ct,all} = 1.5 \text{ N/mm}^2$.

Solution

Calculation of geometric properties

The section is divided into three rectangles for the computation of the geometric properties. The centroid of each rectangle is located from the soffit.



Area of the section

Area of 1 = $A_1 = 500 \times 200$ = 100,000 mm² Area of 2 = $A_2 = 600 \times 150$ = 90,000 mm² Area of 3 = $A_3 = 250 \times 200$ = 50.000 mm²

$$A = A_1 + A_2 + A_3$$

= 240,000 mm²

Location of CGC from the soffit

$$\overline{y} = \frac{A_1 \times 900 + A_2 \times 500 + A_3 \times 100}{A}$$

= 583.3 mm

Therefore,

 $y_b = 583.3 \text{ mm}$ $y_t = 1000.0 - 583.3$ = 416.7 mm

Eccentricity of CGS at mid-span

Moment of inertia of 1

about axis through CGC

$$I_1 = \frac{1}{12} \times 500 \times 200^3 + A_1 \times (900 - 583.3)^2$$

= 1.036 × 10¹⁰ mm⁴

Moment of inertia of

2

about axis through CGC

$$I_2 = \frac{1}{12} \times 150 \times 600^3 + A_2 \times (583.3 - 500)^2$$

= 3.32 × 10⁹ mm⁴

Moment of inertia of

3 about axis through CGC

$$I_3 = \frac{1}{12} \times 250 \times 200^3 + A_3 \times (583.3 - 100)^2$$

= 1.184 × 10¹⁰ mm⁴

Moment of inertia of the section

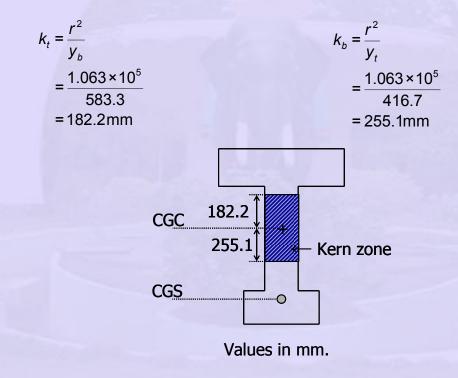
$$I = I_1 + I_2 + I_3$$

= (1.036 + 0.336 + 1.184) × 10¹⁰
= 2.552 × 10¹⁰ mm⁴

Square of the radius of gyration

$$r^{2} = \frac{I}{A}$$
$$= \frac{2.552 \times 10^{10}}{240,000}$$
$$= 1.063 \times 10^{5} \text{ mm}^{2}$$

a) Kern levels of the section



Calculation of moment due to self weight (M_{DL}) .

$$w_{DL} = 24.0 \text{ kN/m}^3 \times 240,000 \text{ mm}^2 \times \left(\frac{1}{10^3}\right)^2 \frac{\text{m}^2}{\text{mm}^2}$$

= 5.76 kN/m
$$M_{DL} = \frac{w_{DL}L^2}{8}$$

= $\frac{5.76 \times 18.0^2}{8}$
= 233.3 kNm

b) Calculation of cracking moment

Modulus of rupture

$$= 0.7\sqrt{30}$$

 $f_{cr} = 0.7\sqrt{f_{ck}}$

= 3.83kN/mm²

$$M_{cr} = \frac{f_{cr}I}{y_b} + \frac{P_eI}{Ay_b} + P_ee$$

= $\frac{3.83 \times 2.552 \times 10^{10}}{583.3} + \frac{0.85 \times 1600 \times 10^3 \times 2.552 \times 10^{10}}{240 \times 10^3 \times 583.3} + 0.8 \times 1600 \times 10^3 \times 433.3 \text{ Nmm}$
= 167.6 + 247.9 + 554.6
= 970.1 kNm

Live load moment corresponding to cracking

$$M_{LL cr} = 970.1 - 233.3$$

= 736.8 kNm

Since the given live load moment (648.0 kNm) is less than the above value, the section is uncracked.

 \Rightarrow The moment of inertia of the gross section can be used for computation of stresses.

c) Calculation of location of pressure line at mid-span

At transfer

$$z = \frac{M_{DL}}{C}$$

$$= \frac{233.3 \times 10^{3}}{1600}$$

$$= 145.8 \text{ mm}$$

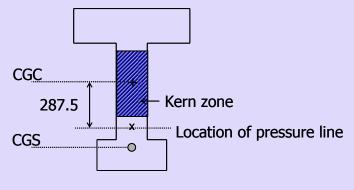
$$e_{c} = z - e$$

$$= 145.8 - 433.3$$

$$= -287.5 \text{ mm}$$

Since e_c is negative, the pressure line is below CGC.

Since the magnitude of e_c is greater than k_b , there is tension at the top.



Value in mm.

At service

$$z = \frac{M_{DL+LL}}{C}$$

$$= \frac{(233.3 + 648.0) \times 10^{3}}{0.85 \times 1600}$$

$$= 648.0 \text{ mm}$$

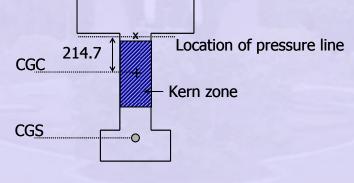
$$e_{c} = z - e$$

$$= 648.0 - 433.3$$

$$= 214.7 \text{ mm}$$

Since e_c is positive, the pressure line is above CGC.

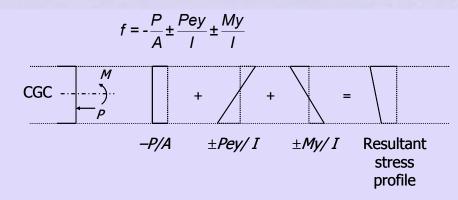
Since the magnitude of e_c is greater than k_t , there is tension at the bottom.





d) Calculation of stresses

The stress is given as follows.



Calculation of stresses at transfer ($P = P_0$)

$$\frac{P_0}{A} = -\frac{1600 \times 10^3}{240 \times 10^3}$$
$$= -6.67 \,\text{N/mm}^2$$

Stress at the top fibre

$$\frac{P_0 ey_t}{I} = \frac{1600 \times 10^3 \times 433.3 \times 416.7}{2.552 \times 10^{10}}$$
$$= 11.32 \text{ N/mm}^2$$
$$\frac{M_{DL}y_t}{I} = -\frac{233.3 \times 10^6 \times 416.7}{2.552 \times 10^{10}}$$
$$= -3.81 \text{ N/mm}^2$$
$$\therefore f_{c_i} = -6.67 + 11.32 - 3.81$$
$$= 0.84 \text{ N/mm}^2$$

Stress at the bottom fibre

$$\frac{P_0 ey_b}{I} = -\frac{1600 \times 10^3 \times 433.3 \times 583.3}{2.552 \times 10^{10}}$$
$$= -15.85 \text{ N/mm}^2$$
$$\frac{M_{DL}y_b}{I} = \frac{233.3 \times 10^6 \times 583.3}{2.552 \times 10^{10}}$$
$$= 5.33 \text{ N/mm}^2$$
$$\therefore f_{c_s} = -6.67 - 15.85 + 5.33$$
$$= -17.19 \text{ N/mm}^2$$

Calculation of stresses at service $(P = P_e)$

$$\frac{P_e}{A} = 0.85 \frac{P_0}{A}$$
$$= -5.67 \text{ N/mm}^2$$

Stress at the top fibre

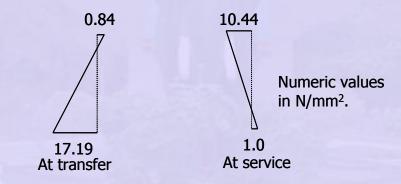
$$\frac{P_{f}ey_{t}}{I} = 0.85 \times 11.32$$
$$= 9.62$$
$$\frac{M_{LL}y_{t}}{I} = -\frac{648.0 \times 10^{6} \times 416.7}{2.552 \times 10^{10}}$$
$$= -10.58 \text{ N/mm}^{2}$$

$$f_{c_i} = -5.67 + 9.62 - 3.81 - 10.58$$
$$= -10.44 \text{ N/mm}^2$$

Stress at the bottom fibre

$$\frac{P_{f}ey_{b}}{I} = -0.85 \times 15.85$$
$$= -13.47 \text{ N/mm}^{2}$$
$$\frac{M_{LL}y_{b}}{I} = \frac{648.0 \times 10^{6} \times 583.3}{2.552 \times 10^{10}}$$
$$= 14.81 \text{ N/mm}^{2}$$
$$\therefore f_{c_{o}} = -5.67 - 13.47 + 5.33 + 14.81$$
$$= 1.0 \text{ N/mm}^{2}$$

The stress profiles are shown.



The allowable stresses are as follows.

For compression,	f _{c,comp}	$= -18.0 \text{ N/mm}^2$
For tension,	f _{c,tens}	= 1.5 N/mm ² .

Thus, the stresses are within the allowable limits.

4.2 Design of Sections for Flexure

This section covers the following topics

- Preliminary Design
- Final Design for Type 1 Members
- Special Case

Calculation of Moment Demand

For simply supported prestressed beams, the maximum moment at the span is given by the beam theory. For continuous prestressed beams, the analysis can be done by moment distribution method. The moment coefficients in **Table 12** of **IS:456 - 2000** can be used under conditions of uniform cross-section of the beams, uniform loads and similar lengths of span.

The design is done for the critical section. For a simply supported beam under uniform loads, the critical section is at the mid span. For a continuous beam, there are critical sections at the supports and at the spans.

For design under service loads, the following quantities are known.

 M_{DL} = moment due to dead load (excluding self-weight)

 M_{LL} = moment due to live load.

The material properties are selected before the design.

The following quantities are unknown.

The member cross-section and its geometric properties,

 M_{SW} = moment due to self-weight,

 A_{p} = amount of prestressing steel,

 P_e = the effective prestress,

e = the eccentricity.

There are two stages of design.

1) **Preliminary**: In this stage the cross-section is defined and P_e and A_p are estimated.

 Final: The values of *e* (at the critical section), *P_e*, *A_p* and the stresses in concrete at transfer and under service loads are calculated. The stresses are checked with the allowable values. The section is modified if required.

4.2.1 Preliminary Design

The steps of preliminary design are as follows.

- 1) Select the material properties f_{ck} and f_{pk} .
- 2) Determine the total depth of beam (*h*).

The total depth can be based on architectural requirement or, the following empirical equation can be used.

$$h = 0.03 \sqrt{M}$$
 to 0.04 \sqrt{M} (4-2.1)

Here, *h* is in meters and *M* is in kNm. *M* is the total moment excluding self-weight.

- Select the type of section. For a rectangular section, assume the breadth b = h/2.
- Calculate the self-weight or, estimate the self-weight to be 10% to 20% of the load carried.
- 5) Calculate the total moment M_T including self-weight. The moment due to self-weight is denoted as M_{sw} .
- 6) Estimate the lever arm (z).

 $z \approx 0.65$ h, if M_{sw} is large ($M_{sw} > 0.3M_T$).

- $z \approx 0.5$ h, if M_{sw} is small.
- 7) Estimate the effective prestress (P_e)

 $P_e = M_T / z$, if M_{sw} is large.

 $P_e = M_{IL} / z$, if M_{sw} is small.

If M_{sw} is small, the design is governed by the moment due to imposed load

$$(M_{IL} = M_T - M_{SW}).$$

- 8) Considering $f_{pe} = 0.7 f_{pk}$, calculate area of prestressing steel $A_p = P_e / f_{pe}$.
- 9) Check the area of the cross-section (*A*).

The average stress in concrete at service C/A (= P_e/A) should not be too high as compared to 50% of the allowable compressive stress $f_{cc,all}$. If it is so, increase the area of the section to $A = P_e/(0.5f_{cc,all})$.

4.2.2 Final Design for Type 1 Members

The code **IS:1343 - 1980** defines three types of prestressed members.

Type 1: In this type of members, no tensile stress is allowed in concrete at transfer or under service loads.

Type 2: In these members, tensile stress is within the cracking stress of concrete.

Type 3: Here, the tensile stress is such that the crack width is within the allowable limit.

The final design involves the checking of the stresses in concrete at transfer and under service loads with respect to the allowable stresses. Since the allowable stresses depend on the type of member (Type 1, Type 2 or Type 3), the equations vary for the different types. Here, the steps of final design are explained for Type 1 members. The steps for Type 2 members are explained in Section 4.3, Design of Sections for Flexure (Part II). The steps for Type 3 members are similar to Type 2, the only difference being the value of the allowable tensile stress in concrete.

For small moment due to self-weight ($M_{sw} \leq 0.3M_T$), the steps are as follows.

1) Calculate eccentricity e to locate the centroid of the prestressing steel (CGS). With increasing load, the compression (C) moves upward from the location of the tension (T) at CGS. At transfer, under the self-weight, C should lie within the kern zone to avoid tensile stress at the top. The kern points and kern zone are explained in Section 3.3, Analysis of Member under Flexure (Part II).

The lowest permissible location of *C* due to self-weight is at the bottom kern point (at a depth k_b below CGC) to avoid tensile stress at the top. The design procedure based on the extreme location of *C* gives an economical section.

The following sketch explains the lowest permissible location of *C* due to self-weight moment (M_{sw}) at transfer.

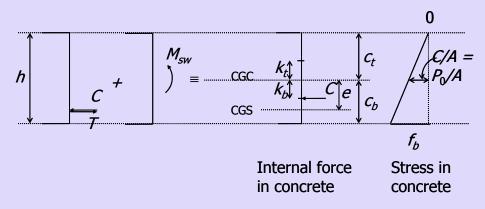


Figure 4-2.1 Stress in concrete due to compression at bottom kern point

In the above sketch,

- A = gross area of cross section
- *f_b* = maximum compressive stress in concrete at bottom edge
- *h* = total height of the section
- k_t , k_b = distances of upper and lower kern points, respectively, from CGC
- c_t , c_b = distances of upper and lower edges, respectively, from CGC
- P_0 = prestress at transfer after initial losses.

The shift of C due to self-weight gives an expression of e.

$$e = (M_{sw} / P_0) + k_b$$
 (4-2.2)

Here, the magnitude of *C* or *T* is equal to P_0 . The value of P_0 can be estimated as follows.

- a) 90% of the initial applied prestress (P_i) for pre-tensioned members.
- b) Equal to P_i for post-tensioned members.

The value of P_i can be estimated from the amount of prestressing steel determined in the preliminary design.

$$P_i = A_p(0.8f_{pk})$$
 (4-2.3)

Here, the permissible prestress in the steel is $0.8f_{pk}$, where f_{pk} is the characteristic tensile strength.

2) Recompute the effective prestress Pe and the area of prestressing steel Ap.

With increasing load, C further moves up. Under the service loads, C should lie within the kern zone to avoid tensile stress at the bottom. The highest permissible location of

C due to total load is at the top kern point (at a height k_t above CGC) to avoid tensile stress at the bottom.

The following sketch explains the highest possible location of *C* due to the total moment (M_T) .

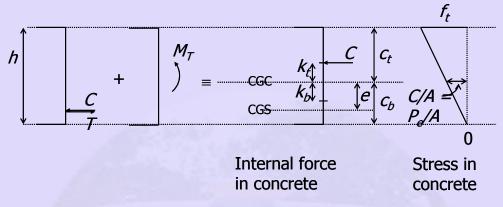


Figure 4-2.2 Stress in concrete due to compression at top kern point In the above sketch,

 f_t = maximum compressive stress in concrete at top edge.

The shift of C due to the total moment gives an expression of P_{e} .

$$P_e = M_T / (e + k_t)$$
 (4-2.4)

Considering $f_{pe} = 0.7 f_{pk}$, the area of prestressing steel is recomputed as follows.

$$A_p = P_e / f_{pe} \tag{4-2.5}$$

3) Recompute eccentricity e

First the value of P_0 is updated. The eccentricity *e* is recomputed with the updated value of P_0 .

If the variation of *e* from the previous value is large, another cycle of computation of the prestressing variables can be undertaken.

4) Check the compressive stresses in concrete.

The maximum compressive stress in concrete should be limited to the allowable values.

At transfer, the stress at the bottom should be limited to $f_{cc,all}$, where $f_{cc,all}$ is the allowable compressive stress in concrete at transfer (available from **Figure 8** of **IS:1343**

- 1980). At service, the stress at the top should be limited to $f_{cc,all}$, where $f_{cc,all}$ is the allowable compressive stress in concrete under service loads (available from Figure 7 of IS:1343 - 1980).

a) At Transfer

The stress at the bottom can be calculated from the average stress $-P_0/A$.

$$f_{b} = -\frac{P_{0}}{A} \frac{h}{c_{t}}$$
(4-2.6)

To satisfy $|f_b| \le f_{cc,all}$, the area of the section (A) is checked as follows.

$$A \ge \frac{P_0 h}{f_{cc,all} c_t}$$
(4-2.7)

If A is not adequate then the section has to be redesigned.

b) At Service

The stress at the top can be calculated from the average stress $-P_e/A$.

$$f_t = -\frac{P_e}{A}\frac{h}{c_b}$$
(4-2.8)

To satisfy $|f_t| \le f_{cc,all}$, the area of the section (A) is checked as follows.

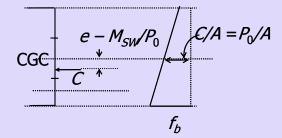
$$A \ge \frac{P_e h}{f_{cc,all} c_b}$$
(4-2.9)

If A is not adequate then the section has to be redesigned.

4.2.3 Special Case

For large moment due to self-weight ($M_{sw} > 0.3 M_T$), the eccentricity *e* according to $e = (M_w / P_0) + k_b$ may violate the cover requirements or, may even lie outside the beam. In such cases, locate e as per cover requirements. The location of *C* at transfer will be within the kern zone without zero stress at the top. The expression of stress at the bottom is different from that given earlier. The other steps are same as before.

At transfer, the stress at the bottom is calculated using the following stress profile.





$$f_{b} = -\frac{P_{0}}{A} - \frac{P_{0} \left(e - \frac{M_{sw}}{P_{0}}\right)c_{b}}{I}$$
(4-2.10)

Substituting $I = Ar^2$ and $r^2/c_b = k_t$

$$f_{b} = -\frac{P_{0}}{A} \left(1 + \frac{e - \frac{M_{sw}}{P_{0}}}{k_{t}} \right)$$
(4-2.11)

To satisfy $|f_b| \le f_{cc,all}$, the area of the section (A) is checked as follows.

$$A \ge \frac{P_0}{f_{cc,all}} \left(1 + \frac{e - \frac{M_{sw}}{P_0}}{k_t} \right)$$
(4-2.12)

The following example shows the design of a Type 1 prestressed member.

Example 4-2.1

Design a simply supported Type 1 prestressed beam with M_T = 435 kNm (including an estimated M_{SW} = 55 kNm). The height of the beam is restricted to 920 mm. The prestress at transfer f_{p0} = 1035 N/mm² and the prestress at service f_{pe} = 860 N/mm².

Based on the grade of concrete, the allowable compressive stresses are 12.5 N/mm^2 at transfer and 11.0 N/mm^2 at service.

The properties of the prestressing strands are given below.

Type of prestressing tendon : 7-wire strandNominal diameter= 12.8 mm

Nominal area = 99.3 mm²

Solution

A) Preliminary design

The values of h and M_{SW} are given.

1) Estimate lever arm z. $\frac{M_{sw}}{M_{\tau}} = \frac{55}{435}$ = 12.5 %

Since $M_{SW} < 0.3 M_T$,

Use z = 0.5h= 0.5 × 920 = 460 mm

2) Estimate the effective prestress.

Moment due to imposed loads

$$M_{IL} = M_{\tau} - M_{sw}$$

= 435 - 55
= 380 kNm

Effective prestress

$$P_e = \frac{380 \times 10^3}{460}$$

= 826 kN

3) Estimate the area of the prestressing steel.

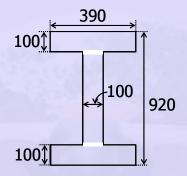
$$A_{p} = \frac{P_{e}}{f_{pe}}$$
$$= \frac{826 \times 10^{3}}{860}$$
$$= 960 \text{ mm}^{2}$$

4) Estimate the area of the section to have average stress in concrete equal to 0.5 $f_{cc,all}$.

$$A = \frac{P_e}{0.5f_{cc,all}} = \frac{826 \times 10^3}{0.5 \times 11.0} = 150 \times 10^3 \text{ mm}^2$$

The following trial section has the required depth and area.

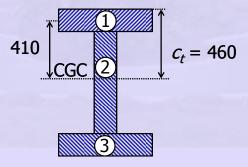
Trial cross-section



Values in mm.

B) Calculation of geometric properties

The section is symmetric about the horizontal axis. Hence, the CGC lies at mid depth. The section is divided into three rectangles for the computation of the geometric properties.



Values in mm.

Check area of the section

$$A = 2A_1 + A_2$$

= 2 × (390 × 100) + (720 × 100)
= 150,000 mm²

Moment of inertia of the section about axis through CGC

$$I = 2I_1 + I_2$$

= $2\left[\frac{1}{12} \times 390 \times 100^3 + (390 \times 100) \times 410^2\right] + \frac{1}{12} \times 100 \times 720^3$
= $1.6287 \times 10^{10} \text{ mm}^4$

Square of the radius of gyration

$$r^{2} = \frac{I}{A}$$
$$= \frac{1.6287 \times 10^{10}}{150,000}$$
$$= 108,580 \,\mathrm{mm}^{2}$$

Kern levels of the section

$$k_t = k_b = \frac{r^2}{c_t}$$

= $\frac{108,580}{460}$
= 236 mm

Summary after preliminary design

Properties of section

$$A = 150,000 \text{ mm}^2$$

$$I = 1.6287 \times 1010 \text{ mm}^4$$

$$c_t = c_b = 460 \text{ mm}$$

$$k_t = k_b = 236 \text{ mm}$$
Properties of prestressing steel
$$A_p = 960 \text{ mm}^2$$

$$P_e = 826 \text{ kN}$$

C) Final design

1) Calculate eccentricity e

$$P_{0} = A_{p}f_{p0} \qquad e = \frac{M_{sw}}{P_{0}} + k_{b}$$

= 960 × 1035
= 993.6 kN
$$= \frac{55.0 \times 10^{3}}{993.6} + 236$$

 $\approx 290 \text{ mm}$

2) Recompute the effective prestress and associated variables.

$$P_{e} = \frac{M_{T}}{e + k_{t}}$$
$$= \frac{435 \times 10^{3}}{(290 + 236)}$$
$$= 827 \text{ kN}$$

Since P_e is very close to the previous estimate of 826 kN, A_p , P_0 and e remain same.

The tendons are placed in two ducts. The outer diameter of each duct is 54 mm.

Select (10) 7-wire strands with

$$A_p = 10 \times 99.3$$

= 993.0 mm²

3) Check the compressive stresses in concrete.

a) At transfer

$$A \ge \frac{P_0 h}{f_{cc,all} c_t}$$
$$= \frac{993.6 \times 920}{12.5 \times 460}$$
$$= 158,976 \text{ mm}$$

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b) At service

$$A \ge \frac{P_e h}{f_{cc,all} C_b}$$
$$= \frac{827 \times 920}{11.0 \times 460}$$
$$= 150,364 \text{ mm}^2$$

The governing value of *A* is 158,976 mm². The section needs to be revised. The width of the flange is increased to 435 mm. The area of the revised section is 159,000 mm².

Another set of calculations can be done to calculate the geometric properties precisely.

Designed cross-section at mid-span

