

KANI'S METHOD

* Kani, a German engineer developed another distribution p.o. based on slope deflection equations

* This method is very useful for the analysis of multi-story frames (3 to 4 stories) even today.

* This method is first explained for structures with fixed ends modified for simply and overhanging supports.

* Sign Conventions:-

- All clockwise moments are positive
- clockwise rotations are positive

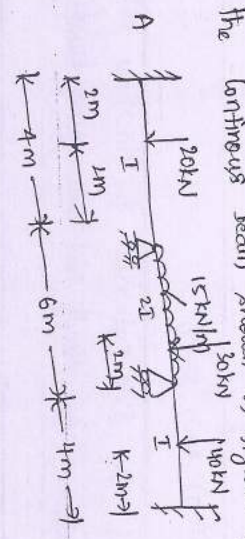
* Rotation factor (RF):-

$$R.F = -\frac{1}{2} \frac{k}{\sum K}$$

Application of Kar's method to continuous beams with fixed ends

The above procedure may be applied to continuous beams with fixed ends resting that the rotation contribution at the end is zero, since the end is being fixed, its rotation is zero.

Analyze the continuous beam shown in figure by Kar's method.



Fixed end moments:

$$M_{FAB} = -\frac{20 \times 2^2}{8} = -10 \text{ kNm}$$

$$M_{FBI} = +10 \text{ kNm}$$

$$M_{FBC} = -\frac{15 \times 6^2}{12} - \frac{30 \times 4 \times 2^2}{6} = -58.33 \text{ kNm}$$

$$M_{FCB} = \frac{15 \times 6^2}{12} + \frac{30 \times 4 \times 2^2}{6} = 21.67 \text{ kNm}$$

$$M_{PCD} = -\frac{10 \times 4^2}{8} = -20 \text{ kNm}$$

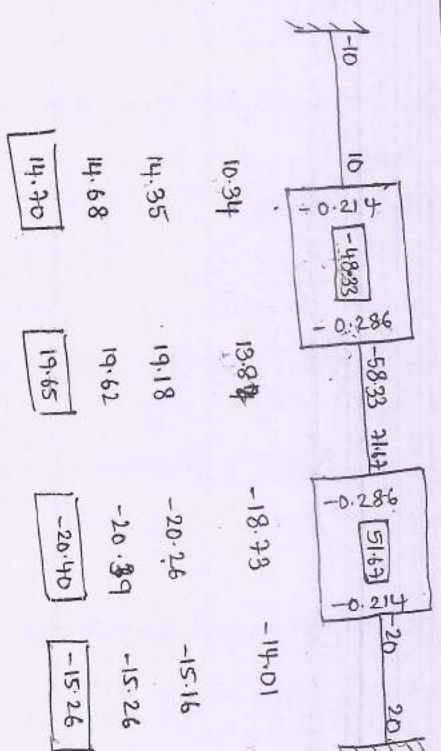
$$M_{PCD} = 20 \text{ kNm}$$

∴ Rotation factors:

$$R.F = \frac{-1}{2} \frac{k}{k}$$

B	BA	$\frac{4EI}{4} = EI$	2.33EI	0
B	BC	$\frac{4EI(2)}{6} = \frac{4}{3}EI$	2.33EI	0
C	CB	$\frac{4EI}{4} = EI$	2.33EI	0
C	CD	$\frac{4EI}{4} = EI$		0

Rotation Contribution table:



$$M_{I1} = 0 \quad -0.214 [-48.33 + 0] = 10.94 \quad -0.286 [-48.33 + 0] = 13.87$$

$$M_{I2} = 0 \quad -0.214 [51.67 + 18.33] = -14.01 \quad -0.286 [51.67 + 18.33] = -19.16$$

$$M_{I3} = 0 \quad -0.214 [-48.33 - 18.33] = 14.35 \quad -0.286 [-48.33 - 18.33] = 19.62$$

$$M_{I4} = 0 \quad -0.214 [51.67 + 19.18] = -15.1 \quad -0.286 [51.67 + 19.18] = -20.39$$

$$M_{I5} = 0 \quad -0.214 [-48.33 - 20.26] = 14.68 \quad -0.286 [-48.33 - 20.26] = 19.62$$

$$M_{I6} = 0 \quad -0.214 [-48.33 + 19.62] = -15.1 \quad -0.286 [-48.33 + 19.62] = -20.39$$

$$-0.286 [51.67 + 19.65] = -20.40$$

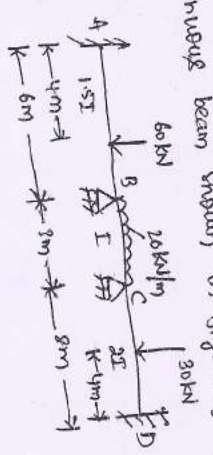
$$-0.214 [51.67 + 19.65] = -15.26$$

Final moment calculation :-

FEM = FEM + 2 (near end contribution) + far end value

Joints	A	B	C	D
FEM	-10	10	-58.33	21.67
NEC	2x0	2x14.7	2x19.65	2x-20.40
FEC	14.70	0	-20.40	19.65
Final	4.70	39.14	-39.14	50.52

Analyze the continuous beam shown in figure by karis method



Fixed end moments

$$M_{FAB} = \frac{-60 \times 4 \times 2^2}{6^2} = -26.67 \text{ kNm}$$

$$M_{FBA} = \frac{60 \times 4^2 \times 2}{6^2} = 53.33 \text{ kNm}$$

$$M_{FBC} = \frac{-20 \times 8^3}{12} = -106.67 \text{ kNm}$$

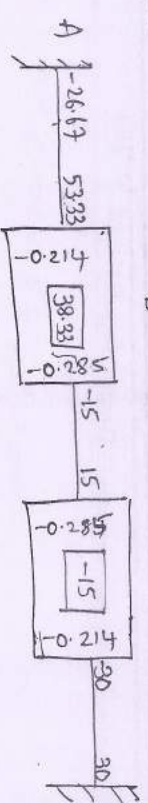
$$M_{FCB} = 15 \text{ kNm}$$

$$M_{FCD} = \frac{-30 \times 8^2}{8} = -36 \text{ kNm}$$

$$M_{DC} = +30 \text{ kNm}$$

Joints	members	k	Zk	R
B	BA	$\frac{4E(15^2)}{6} = 153.33EI$	2.333EI	-
	BC	$\frac{4E(8^2)}{3} = 133.33EI$	2.333EI	-
	CB	133.33EI	2.333EI	-
	CD	$\frac{4E(8^2)}{8} = 66.67EI$	2.333EI	-

Rotation table



-26.67	53.33	-15	15	-15	30
-8.20	-10.92	8.38	5.54		
-9.18	-13.02	8.00	6.00		
-9.91	-13.20	8.03	6.03		
-9.92	-13.21	8.04	6.04		

Final moment calculation :-

FM = FEM + 2x near end contribution + far end

Joints	A	B	C	D
FEM	-26.67	53.33	-15	15
NEC	2x0	2x-9.92	2x8.04	2x6.04
FEC	-9.92	0	8.04	6.04
Final moment	-36.60	33.49	-33.4	36.04

Application to continuous beams with simply supported end

Overhanging Ends:

METHOD 1: If the end of the continuous beam is simply supported & has overhang, the last support also rotates. Hence rotation contribution of that joint also should be found. Stiffness of overhanging portion may be taken as zero, since the moment in this portion does not depend upon the loading in the other portion. Then, rotation factor for internal member at such joint is -0.5.

METHOD - 2:

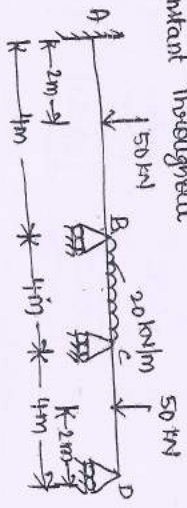
$$K = \frac{3EI}{L}$$

FEM at the simply supported end is zero

$$M_{FAB} = M_{FBA} + 0.5 \times \text{bending moment at B}$$

$$= M_{FAB} - 0.5 \times \text{in balancing moment at B}$$

* Analyse the continuous beam shown by Kar's method. Flexural rigidity is constant throughout



Fixed end moments:

$$M_{FAB} = -\frac{50 \times 4}{8} = -25 \text{ kNm}$$

$$M_{FBA} = 25 \text{ kNm}$$

$$M_{FBC} = -\frac{20 \times 4^2}{12} = -26.6 \text{ kNm}$$

$$M_{FCD} = 25 \text{ kNm}$$

$$M_{FCB} = 26.6 \text{ kNm}$$

METHOD - 3

modification of FEM in the last span is required

$$M_{FCD} = M_{FCB} - 0.5 \times \text{unbalanced moment at C}$$

$$= -25 - 0.5(25) = -37.5 \text{ kNm}$$

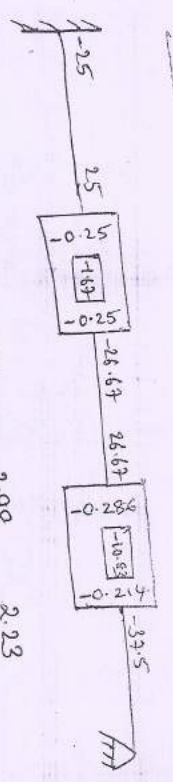
$$M_{PDC} = 0$$

$$R.F. = -\frac{1}{2} \left(\frac{EK}{EK} \right)$$

$$K \text{ in span } CD = \frac{3EI}{4}$$

Rotation Factors:

Joints	members	K	EK	R
B	BA	$\frac{4EI}{4} = EI$	2EI	-
	BC	$\frac{4EI}{4} = EI$	-	-
C	CB	$\frac{4EI}{4} = EI$	1.75EI	-
	CD	$\frac{3EI}{4} = 0.75EI$	-	-



Fixed end moments

$$M_{FAB} = \frac{-30 \times 4^2}{12} = -40 \text{ kNm}$$

$$M_{FBA} = 40 \text{ kNm}$$

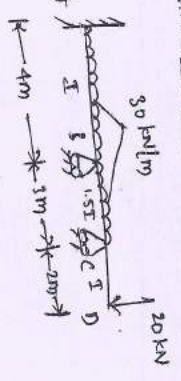
$$M_{FBC} = \frac{-30 \times 3^2}{12} = -22.5 \text{ kNm}$$

$$M_{FCD} = -20 \times 2 = -40 \text{ kNm}$$

Final moment calculations

	A	B	C	D
FEM	-25	25	-26.67	26.67
NEC	2x0	2(-0.38)	2(0.38)	2(1.22)
PEC	-0.38	0	-0.38	0
Final	-25.38	24.24	-24.24	32.91

* Analyse the continuous beam shown in figure



Final moment calculations

	A	B	C	D
FEM	-40	40	-13.5	13.5
NEC	2x0	2(-5.3)	2(1.95)	2(1.95)
PEC	-5.3	0	-1.95	0
Final	-45.33	35.66	-29.40	40

R.F.S

Rotation factor $RF = -\frac{1}{2} \left(\frac{k}{\sum k} \right)$

$M_{FBC} = 40 \text{ kNm}$

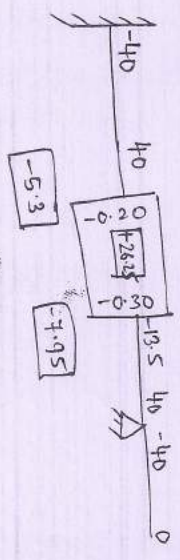
$M_{FBC} = -20.5 - 0.5 (20.5 - 40) = -15.5 \text{ kNm}$

Rotation members R SR R.R

$4EI = EI$

$3EI(5) = 15EI$

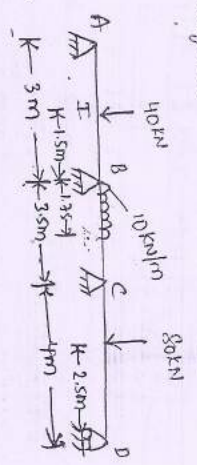
-0.3



Final moment calculations

	A	B	C	D
FEM	-40	40	-13.5	13.5
NEC	2x0	2(-5.3)	2(1.95)	2(1.95)
PEC	-5.3	0	-1.95	0
Final	-45.33	35.66	-29.40	40

through the members are given by



constant throughout

Fixed end moments

$$M_{FAB} = -\frac{40 \times 3^2}{8} = -15 \text{ kNm}$$

$$M_{FBA} = +15 \text{ kNm}$$

$$M_{FBC} = -\int_0^{1.35} \frac{10 dx (3.5-x)^2}{3.5^2} = \left[\frac{10x(1-x)^3}{3} \right]_0^{1.35}$$

$$= \frac{-10}{3.5^2} \int_0^{1.35} (3.5^2 x^2 - 7x^3 + x^3) dx$$

$$= \frac{-10}{3.5^2} \left[3.5^2 \left(\frac{x^3}{3} \right) - 7 \left(\frac{x^4}{4} \right) + \frac{x^4}{4} \right]_0^{1.35}$$

$$= -22.33 \text{ kNm}$$

$$M_{FCB} = \int_0^{1.35} \frac{10x(3.5-x)}{3.5^2} dx$$

$$= \frac{10}{3.5^2} \int_0^{1.35} (3.5x - x^2) dx$$

$$= \frac{10}{3.5^2} \left[3.5 \left(\frac{x^2}{2} \right) - \frac{x^3}{3} \right]_0^{1.35}$$

$$= 3.19 \text{ kNm}$$

$$M_{FCD} = -\frac{80 \times 1.5 \times 2.5^2}{4^2} = -46.88 \text{ kNm}$$

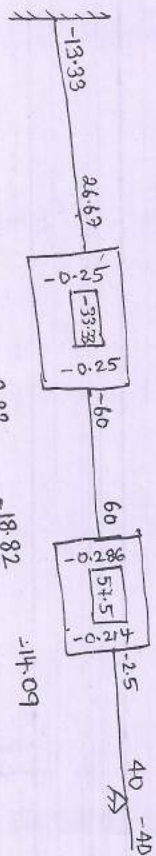
Modification to account for rotation A & D

$$M_{FAB} = 0 \quad M_{FDC} = 0$$

$$M_{FAA} = 15 - 0.5(-15) = 22.5 \text{ kNm}$$

$$M_{FCB} = -46.88 - 0.25 \times 3.19 = -60.95 \text{ kNm}$$

Joint	members	K	ZK	R.F
B	BA	$\frac{4EI}{3} = 133EI$	$\frac{8}{3}EI$ 2.66EI	-0.25
	BC	$\frac{4E(2I)}{6} = \frac{4}{3}EI$ $= 133EI$		-0.25
	CB	$\frac{4E(2I)}{6} = \frac{4}{3}EI$	2.33EI	-0.214
	CD	$\frac{3EI}{3} = EI$		

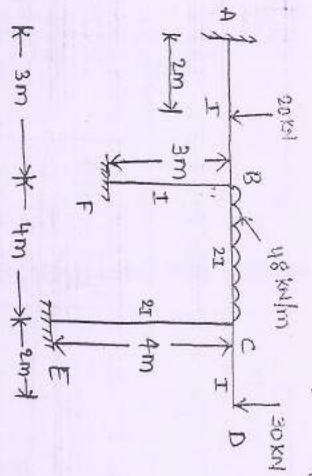


8.33	8.33	-18.82	-14.09
13.04	13.04	-20.17	-15.10
13.38	13.38	-20.27	-15.17
13.40	13.40	-20.27	-15.17

Final moment calculations

	A	B	C	D	E
FEM	-13.33	26.67	-60	60	-2.5
2XND		$2 \times (13.40)$	$2 \times (13.40)$	$2 \times (20.27)$	$2 \times (15.17)$
PEC	13.40	0	-20.28	13.40	0
Final	0.07	53.47	-53.48	32.86	-32.84
				40	-40

modify the sign figure given in figure by Karim's



Fixed end moments:-

$$M_{FAB} = \frac{-20 \times 2 \times 1^3}{3^2} = -4.44 \text{ kNm}$$

$$M_{FBA} = \frac{20 \times 2^2 \times 1}{3^2} = 8.89 \text{ kNm}$$

$$M_{FBC} = \frac{-48 \times 4^3}{12} = -64 \text{ kNm}$$

$$M_{FCB} = 64 \text{ kNm}$$

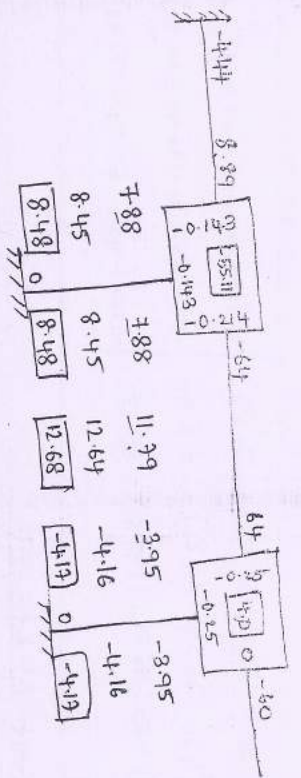
$$M_{FCD} = -30 \times 2 = -60 \text{ kNm}$$

$$M_{FBC} = M_{FCB} = M_{FCE} = M_{FEC} = 0$$

$$\text{Rotation factor (RF)} = -\frac{1}{2} \left(\frac{K}{\sum K} \right)$$

Rotation factors:-

Joint	members	K	ZK	R.F
B	BA	$\frac{4EI}{3} = 133EI$		-0.143
	BF	$\frac{4EI}{3} = 133EI$		-0.143
	BC	$\frac{4E(2I)}{6} = 2EI$		-0.214
	CB	$2EI$		-0.215
	CD	0	4EI	0
	CE	$\frac{4E(2I)}{4} = 2EI$		-0.25



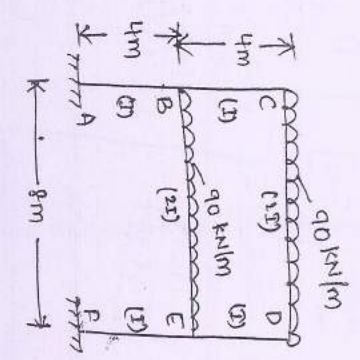
Final moments

Joints	A			B			C			D		E		F	
Members	AB	BA	BF	BC	CB	CE	CD	EC	ED	EF	FD	DE	DF	FE	
MEM	-4.44	8.89	0	-64	64	0	-60	0	2x0	2x0	0	2x0	2x0	0	
KN/EC	2x0	2x8.48 (2x12.64)	2x8.48 (2x12.64)	2(-4.16) (2(-4.16))	2(4.16) (2(4.16))	2x0	2x0	2x0	2x0	2x0	2x0	2x0	2x0	2x0	
FEC	8.48	0	0	-4.16	12.68	0	0	-4.16	-4.16	8.48	0	8.48	0	8.48	
Final	4.04	25.85	16.96	-42.81	68.34	-8.34	-60	-4.16	-4.16	8.48	0	8.48	0	8.48	

$M_{FAB} = -4.44 + 2 \times 0 + 8.48 = 4.04 \text{ kNm}$
 $M_{FBA} = 8.89 + 2 \times 8.48 + 0 = 25.85 \text{ kNm}$
 $M_{FBC} = 0 + 2 \times 8.48 + 0 = 16.96 \text{ kNm}$

$M_{FCB} = -64 + 2 \times 12.68 - 4.16 = -42.81 \text{ kNm}$
 $M_{BC} = -64 + 2(-4.16) + 12.68 = 68.34 \text{ kNm}$
 $M_{CD} = -60 \text{ kNm}$
 $M_{CE} = 0 + 2(-4.16) + 0 = -8.34 \text{ kNm}$
 $M_{EC} = 0 + 2 \times 0 - 4.16 = -4.16 \text{ kNm}$
 $M_{FE} = 0 + 2 \times 0 + 8.48 = 8.48 \text{ kNm}$

Draw the symmetric frame shown in figure by hand and indicate the final end moments on the sketch of the



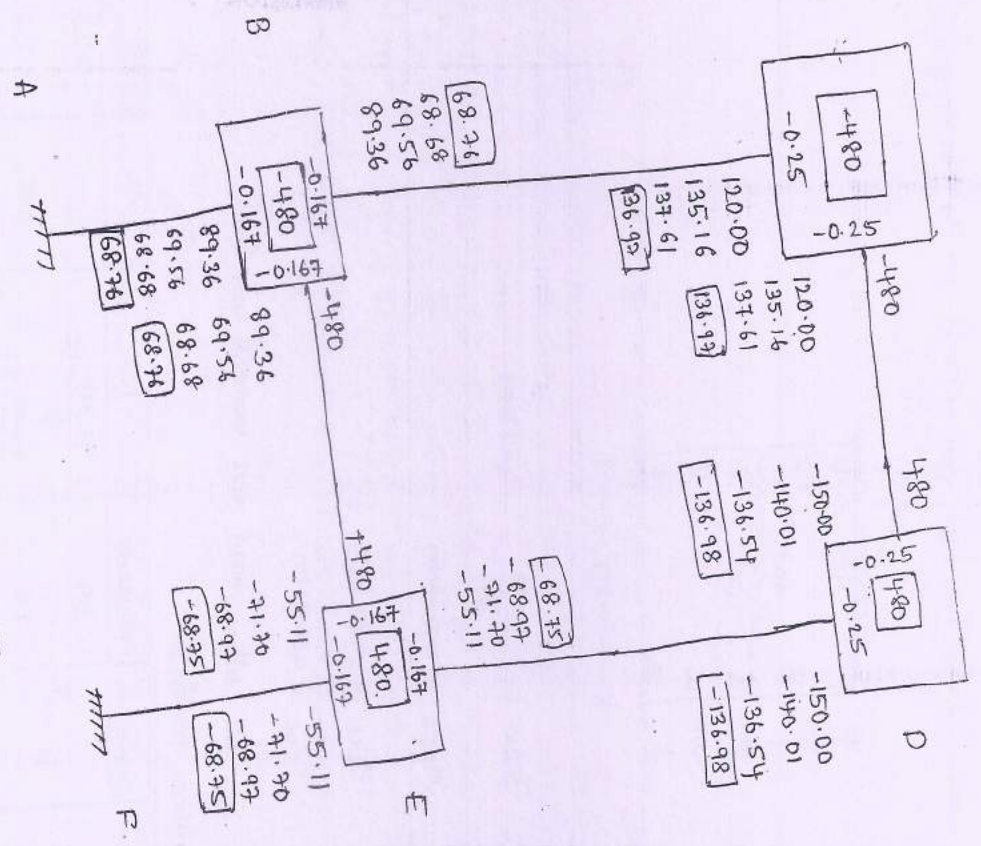
$M_{FBE} = -90 \times 8^2 \times \frac{1}{12} = -480 \text{ kNm}$
 $M_{FEB} = 480 \text{ kNm}$
 $M_{FCD} = -480 \text{ kNm}$
 $M_{FDC} = 480 \text{ kNm}$

Rotations factors:-

Joints	Members	K	ZK	K.P
B	BA	$\frac{4EI(8)}{8} = EI$	3EI	-0.167
	BE	$\frac{4EI(8)}{8} = EI$	3EI	-0.167
	BC	$\frac{4EI}{4} = EI$	3EI	-0.167
C	CB	$\frac{4EI}{4} = EI$	2EI	-0.25
	CD	$\frac{4EI(8)}{8} = EI$	2EI	-0.25
D	DC	$\frac{4EI(8)}{8} = EI$	2EI	-0.25
	DE	$\frac{4EI}{4} = EI$	3EI	-0.167
E	ED	$\frac{4EI}{4} = EI$	3EI	-0.167
	EF	$\frac{4EI(8)}{8} = EI$	3EI	-0.167

$-0.25 (-480 + 0) = 120$
 $-0.25 (480 + 120) = -150$
 $-0.167 (480 + 150) = -55.11$
 $-0.167 (-480 - 55.11) = 89.36$

$-0.25 (480 + 89.36) = 135.16$
 $-0.25 (480 + 135.16) = -140.01$
 $-0.167 (480 + 140.01 + 89.36) = -11.90$
 $-0.167 (-480 - 11.90 + 89.36) = 69.56$



$-0.25 (480 + 137.61 - 91.70) = -136.54$
 $-0.167 (480 - 136.54 + 69.56) = -68.97$
 $-0.167 (-480 - 68.97 + 137.61) = 68.68$

Final moment calculations :-

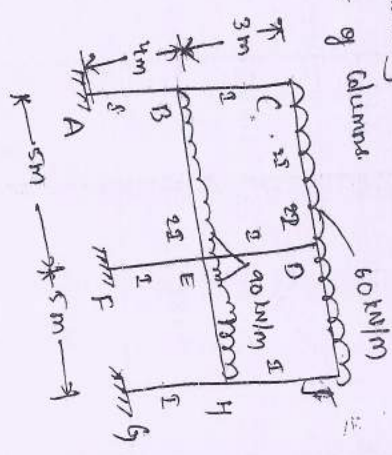
FM = FEM + 2xNEC + FEC

Joint	A	B	C	D	E
Members	AB	BA	BC	CB	CD
FEM	0	0	0	0	0
2xNEC	0	2x68.76	2x68.76	2x11.90	2x
FEC	68.76	0	-68.97	136.98	-68.97
Final	68.76	137.52	-41.25	274.49	542.7

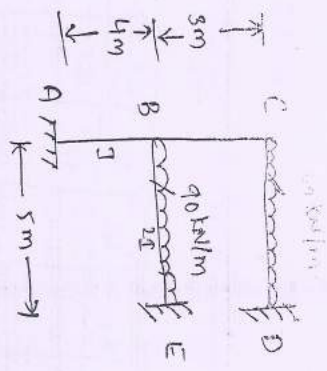
Frames with symmetry do not have side sway such a case occurs when the number of bays are even the mid-span of the beams. Such a case occurs when the number of bays are odd.

Analysis of symmetric frames when line of symmetry passes through columns. Because of symmetry, the joints on the line of symmetry do not rotate. Hence they may be treated as fixed ends and only one half may be analysed. Using symmetry, the bending moment in the columns through which the line of symmetry passes. Make use of the

symmetry for the analysis given that the 2 of become one-half that of column.



Since, the line of symmetry passes through the columns DEF, joints D and E also will not rotate. only one half of frame may be considered as shown in figure.



Fixed end moments

$$M_{FD} = \frac{-60 \times 5^2}{12} = -125$$

$$M_{DC} = 125 \text{ kNm}$$

$$M_{BE} = \frac{-90 \times 5^2}{12} = -187.5$$

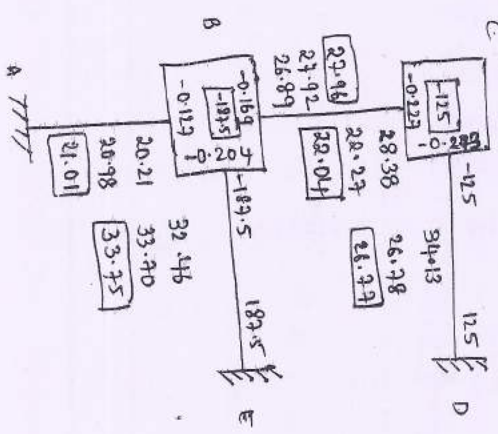
$$M_{EB} = 187.5 \text{ kNm}$$

Fixed end moment at other ends = 0

Rotation factors (RF) = $-\frac{1}{2} \left(\frac{k}{\sum k} \right)$

Joint	Members	K	ΣK	R.F
B	BA	$\frac{4EI}{4} = EI$	3.93 EI	-0.127
	BE	$\frac{4E(90)}{5} = 144EI$		-0.204
C	CB	$\frac{4E(90)}{3} = 135EI$	2.93 EI	-0.227
	CD	$\frac{4E(25)}{5} = 16EI$		-0.223

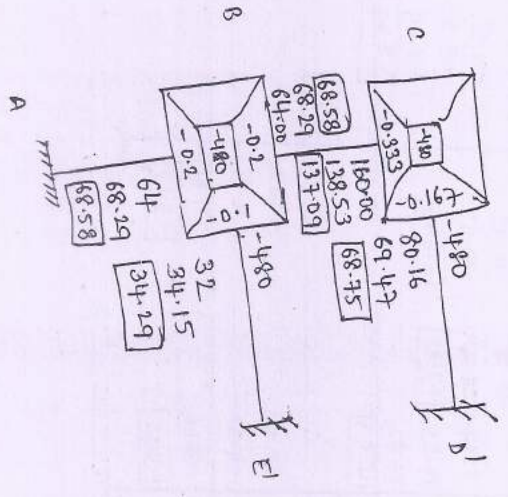
Rotation Contributions:



actions

members

rotations are a considering joint first following which is joint B.



Final moments:

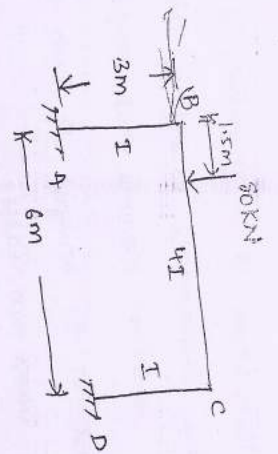
Members	A	B	C	D	E
AB	0	0	0	0	0
BA	0	-480	0	0	0
BC	0	0	0	0	0
CB	0	0	0	0	0
CD	0	0	-480	0	0
DC	0	0	0	0	0
DE	0	0	0	0	0
ED	0	0	0	0	0
PEM	0	0	0	0	0
2XNEC	0	0	0	0	0
PEC	0	0	0	0	0
PM	0	0	0	0	0

Principle of moments

If the frame is unsymmetric, it will laterally, causing relative displacements at ends of columns. lateral sway causes additional moments, which may be called displacement contributions. In the analysis of such frame have sway, we come over two cases:

1. Heights of all columns in a story are the same.
2. Heights of columns in story are different.

Using Matrix Stiffness Method, find the fixed end moments in figure



Fixed end moments :-
 $M_{FBC} = \frac{-80 \times 1.5 \times 4.5^2}{6^2} = -67.5 \text{ kNm}$

$M_{FDB} = \frac{80 \times 1.5^2 \times 4.5}{6^2} = 22.5 \text{ kNm}$

Fixed end moments in both the columns are zero

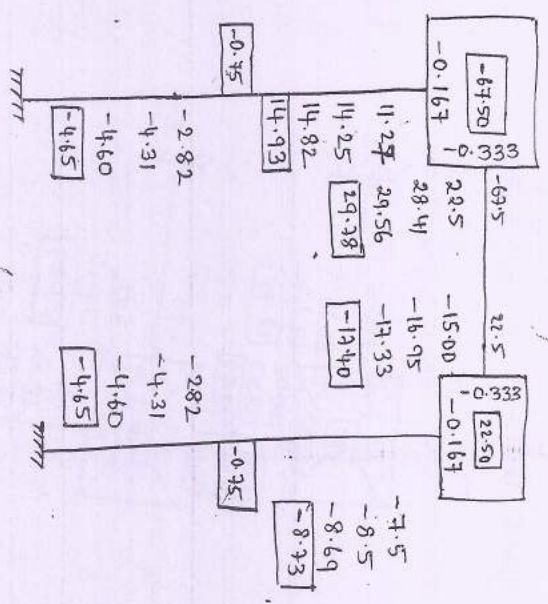
Rotation factor (RF) = $\frac{1}{2} \frac{K}{\sum K}$

Node	Members	K	$\sum K$	RF
B	BI	$\frac{4EI}{3}$	$4EI$	-0.167
B	BC	$\frac{4E(4.5^2)}{6} = 2.67EI$	$4EI$	-0.333
C	CB	$\frac{4E(4.5^2)}{6} = 2.67EI$	$4EI$	-0.333
C	CD	$\frac{4EI}{3}$	$4EI$	-0.167

Displacement factor (DF) = $-\frac{2}{2} \left(\frac{K}{\sum K} \right)$

Node	Members	K	$\sum K$	DF
I	AB	$\frac{4EI}{3} = 1.33EI$	$8EI$	-0.175
I	DC	$\frac{4EI}{3} = 1.33EI$	$8EI$	-0.175

Since, $S_x = 0$, Shear moment = $\frac{1}{3} \times 8 \times 6 = 16$



$-0.167 (-67.50) = 11.27$
 $-0.333 (-67.50) = 22.5$
 $-0.333 (22.50 + 22.50) = -15.00$
 $-0.167 (22.50 + 22.50) = -7.5$
 $-0.167 (-67.50 - 15 - 2.82) = 14.25$
 $-0.333 (-67.50 - 15 - 2.82) = 28.41$
 $-0.333 (22.50 + 22.8 \cdot 4.1) = -16.95$
 $-0.167 (22.50 + 22.8 \cdot 4.1) = -8.5$
 $-0.167 (-67.50 - 16.95 - 4.31) = 14.82$
 $-0.333 (-67.50 - 16.95 - 4.31) = 29.56$
 $-0.333 (22.50 + 29.56) = -17.33$
 $-0.167 (22.50 + 29.56) = -8.69$
 $-0.167 (11.27 - 7.5) = -2.82$
 $-0.175 (14.82 - 8.69) = -4.60$

$$-0.169(-67.50 - 17.33 - 4.60) = 14.43$$

$$-0.333(-67.50 - 17.33 - 4.60) = 29.48$$

$$-0.333(22.50 + 29.98) = -17.40$$

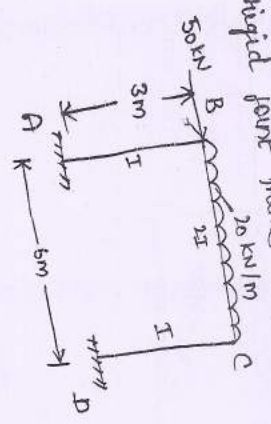
$$-0.169(22.50 + 29.98) = -8.73$$

$$-0.75(14.93 - 8.73) = -4.65$$

2) moment

Joint	A	B	C	D
Members	AB	BA, BC	CB	CD, DC
FEM	0	0, -67.5	22.5	0
2xNEC	2x0	2x14.93	2x29.98	2x0
FEC	14.93, 4.65	-4.65, -17.40	29.98	4.65, -8.73
FM	10.28	25.21, -25.14	17.48	-22.11, -13.38

* Analyse the rigid joint frame shown in figure by Karan's method



fixed end moments:

$$M_{FBC} = -\frac{20 \times 6^2}{12} = -60 \text{ kNm}$$

$$M_{FCB} = \frac{20 \times 6^2}{12} = 60 \text{ kNm}$$

Other FEMs are zero

Rotation at B (RF) = $-\frac{1}{2} \left(\frac{k}{\Sigma K} \right)$

Joint	members	K	ΣK	RF
B	BA, BC	$\frac{4EI}{3} = 1.33EI$ $\frac{4E(25)}{6} = 1.33EI$	2.66EI	-0.25
C	CB, CD	$\frac{4EI}{3} = 1.33EI$	2.66EI	-0.25

Displacement at B (DF) = $-\frac{3}{2} \left(\frac{k}{\Sigma K} \right)$

Story	members	K	ΣK	DF
1	AB, DC	$\frac{4EI}{3} = 1.33EI$ $\frac{4EI}{3} = 1.33EI$	2.66EI	-0.75

Story Shear = 50 kN

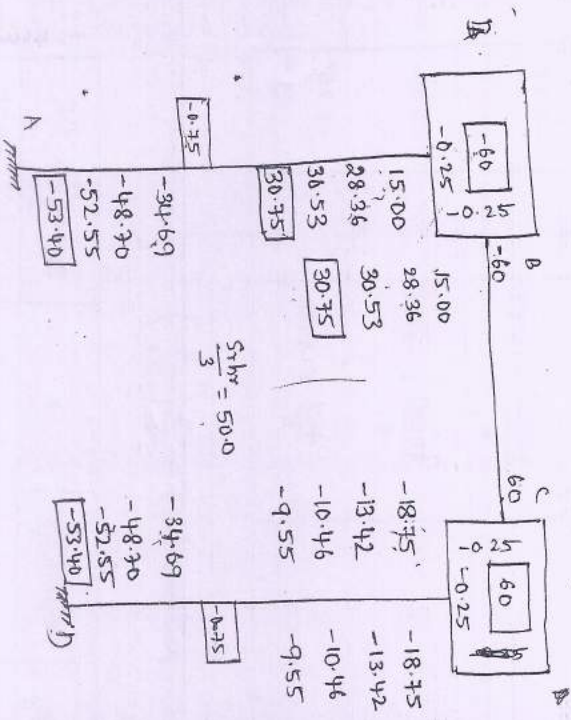
$$\therefore \text{story moment} = \frac{S r h r}{3} = \frac{50 \times 3}{3} = 50 \text{ kNm}$$

Distribution procedure

A) first starts from end B and then proceed C. After obtaining the rotation contributions are to be found

Displacement contribution = DF (story moment + Σ Rotation at top and of the col)

Direction and Distribution:-



I

$$-0.25 (-60 + 0) = 15.00$$

$$-0.25 (60 + 15) = -18.75$$

$$-0.75 (50 + 15 - 18.75) = -34.69$$

II

$$-0.25 (-60 + 18.75 - 34.69) = 28.36$$

$$-0.25 (60 + 28.36 - 34.69) = -13.42$$

$$-0.75 (50 + 28.36 - 13.42) = -48.70$$

III

$$-0.25 (-60 - 13.42 - 48.70) = 30.53$$

$$-0.25 (60 + 30.53 - 48.70) = -10.46$$

$$-0.75 (50 + 30.53 - 10.46) = -52.55$$

Final moments

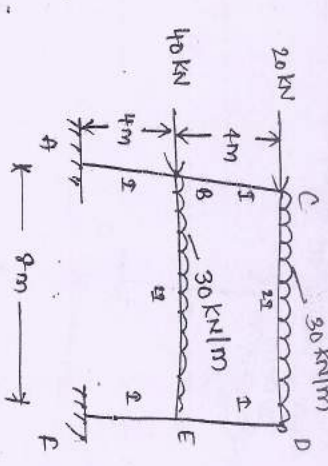
MEM	AB	BA	BC	CB	CD	DC
MEM	0	0	-60	60	0	0
2x0	2x0	2x30.75	2x30.75	-2x9.55	-2x9.55	2x0
PEC	30.75	-53.40	-9.55	30.75	-53.40	-9.55 - 53.40
final moment	-21.65	8.1	-8.05	31.65	-72.5	-62.95

$$-0.25(-60 - 10.46 - 52.55) = 30.75$$

$$-0.25(60 + 30.75 - 52.55) = -9.55$$

$$-0.75(50 + 30.75 - 9.55) =$$

* Analyse the frame shown in figure by karil's method



Final moments in columns = 0

Final moments

$$M_{FAD} = \frac{-30 \times 8^2}{12} = -160 \text{ kNm}$$

$$M_{FDC} = 160 \text{ kNm}$$

$$M_{FBE} = -160 \text{ kNm}$$

$$M_{FEB} = 160 \text{ kNm}$$

$\frac{1}{2} \times \frac{K}{2K}$
 $\frac{1}{2} \times \frac{K}{2K}$

Joint	members	K	ΣK	R.F
B	BA BE BC	$\frac{4EI}{4} = EI$ $\frac{4E(2I)}{8} = EI$ $\frac{4EI}{4} = EI$	3EI	-0.167 -0.167 -0.167
C	CB CD	$\frac{4EI}{4} = EI$ $\frac{4E(2I)}{8} = EI$	2EI	-0.25 -0.25
D	DC DE	$\frac{4E(2I)}{8} = EI$ $\frac{4E(2I)}{4} = EI$	2EI	-0.25 -0.25
E	ED EB EF	EI EI EI	3EI	-0.167 -0.167 -0.167

Displacement factor (DF):-
 $DF = -\frac{3}{2} \frac{K}{2K}$

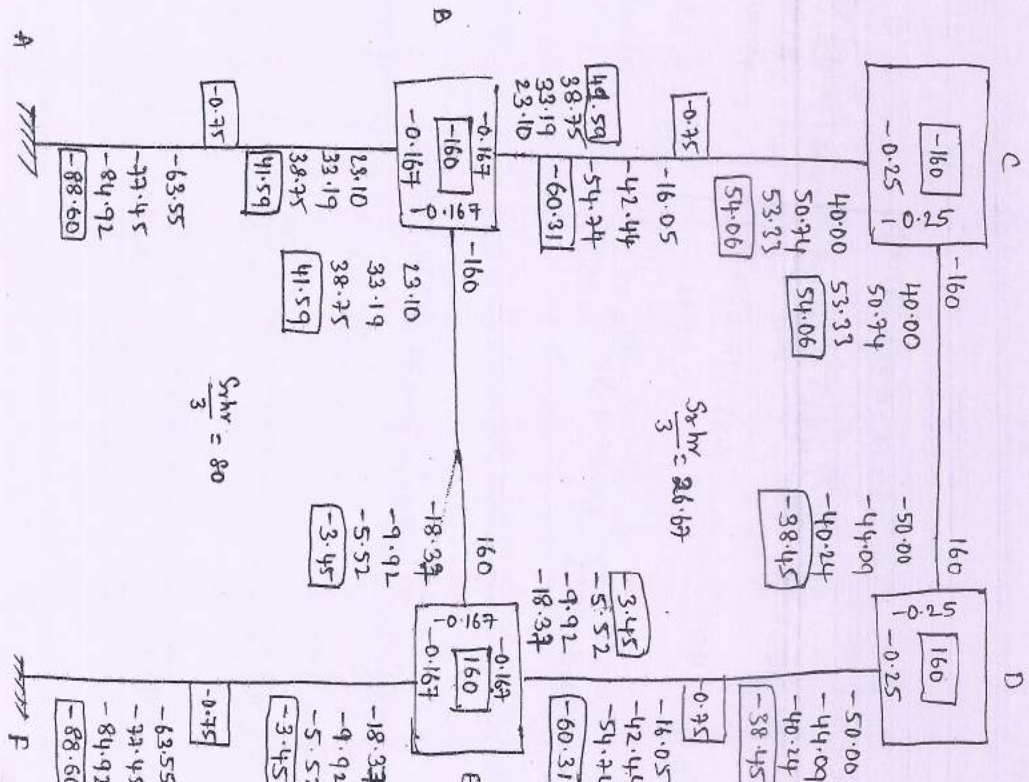
Story	member	K	ΣK	DF
I	AB FE	EI EI	2EI	-0.75 -0.75
II	BC ED	EI EI	2EI	-0.75 -0.75

Story moments

story shear $S_1 = 20 + 40 = 60 \text{ kN}$
 $S_2 = 20 \text{ kN}$

shear moment in story I = $\frac{S_1 h}{3} = \frac{60 \times 4}{3} = 80$
 story II = $\frac{1}{3} S_2 h = \frac{20 \times 4}{3} = 26$

Rotation and Displacement Contributions:-



$$-0.25 (-160 + 0) = 40.00$$

$$-0.25 (-160 + 0) = 40$$

$$-0.25 (160 + 40) = -50$$

$$-0.25 (160 + 40) = -50$$

$$-0.167 (160 - 50) = -18.37$$

$$-0.167 (-160 - 18.37 + 40) = 23.10$$

$$-0.75 (26.67 + 40 - 50 - 18.37 + 23.10) = -16.05$$

$$-0.75 (80 + 23.10 - 18.37) = -63.55$$

$$-0.25 (-160 + 50 + 23.10 - 18.05) = 50.74$$

$$-0.25 (160 + 50 + 23.10 - 18.05) = -44.09$$

$$-0.167 (160 + 44.09 - 18.05 + 23.10 - 63.55) = -9.92$$

$$-0.167 (-160 - 9.92 - 63.55 + 50 - 18.05) = 83.19$$

$$-0.75 (26.67 + 50 + 23.10 - 9.92 - 44.09 + 33.19) = -42.44$$

$$-0.75 (80 + 33.19 - 9.92) = 27.45$$

$$-0.25 (-160 - 44.09 + 33.19 - 42.44) = 53.33$$

$$-0.25 (160 + 53.33 - 9.92 - 42.44) = -40.24$$

$$-0.167 (160 - 40.24 - 42.44 + 33.19 - 27.45) = -5.52$$

$$-0.167 (-160 - 5.52 - 27.45 + 53.33 - 42.44) = 38.25$$

$$-0.75 (26.67 + 53.33 - 5.52 - 40.24 + 38.25) = -54.74$$

$$-0.75 (80 + 38.25 - 5.52) = 84.92$$

$$-0.25 (-160 - 40.24 + 38.25 - 54.74) = 54.06$$

$$-0.25 (160 + 54.06 - 5.52 - 54.74) = -38.45$$

$$-0.167 (160 - 38.45 - 54.74 + 38.25 - 84.92) = 3.45$$

$$-0.167 (-160 - 3.45 - 84.92 + 54.06 - 54.74) = 41.59$$

Fixed moments = FEM + 2xNEC + FEC

$$M_{AB} = 0 + 2 \times 0 + 41.59 - 88.60 = -47.01 \text{ kNm}$$

$$M_{BA} = 0 + 2 \times 41.59 + 0 - 88.60 = -5.42 \text{ kNm}$$

$$M_{BE} = -160 + 2 \times 41.59 - 3.45 + 0 = -80.17 \text{ kNm}$$

$$M_{BC} = 0 + 2 \times 54.06 + 54.06 - 60.31 = 76.93 \text{ kNm}$$

$$M_{CB} = 0 + 2 \times 54.06 + 41.59 - 60.31 = 89.4 \text{ kNm}$$

$$M_{CD} = -160 + 2 \times 54.06 - 38.45 + 0 = -90.33 \text{ kNm}$$

$$M_{DC} = 160 + 2 \times 38.45 + 54.06 + 0 = 137.16 \text{ kNm}$$

$$M_{DE} = 0 - 2 \times 38.45 - 60.31 - 3.45 = -140.66 \text{ kNm}$$

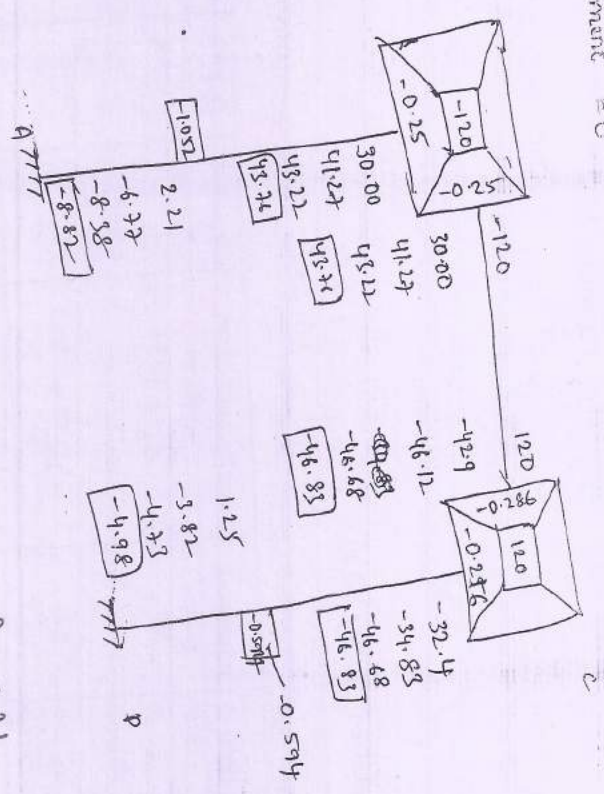
$$M_{ED} = 0 - 2 \times 3.45 - 38.45 - 60.31 = -105.66 \text{ kNm}$$

$$M_{EB} = 160 - 2 \times 3.45 + 41.59 + 0 = 194.7 \text{ kNm}$$

$$M_{EF} = 0 - 2 \times 3.45 - 88.60 = -95.5 \text{ kNm}$$

$$M_{FE} = 0 + 2 \times 0 - 3.45 - 88.60 = -92.05 \text{ kNm}$$

moment = C



$-0.25(-120) = 30.00$
 $-0.286(120 + 30) = 42.9$
 $-0.216(120 + 30) = -32.4$
 $-0.25(-120 + 41.27 - 2.21) = 41.27$
 $-0.286(120 + 41.27) = -46.12$
 $-0.216(120 + 41.27) = -34.83$

$-1.052(30 - 32.4) = 2.21$
 $-0.594(30 - 32.4) = 1.25$
 $-1.052(41.27 - 34.83) = -6.77$
 $-0.594(41.27 - 34.83) = -3.82$
 $-1.052(43.22 - 35.25) = -8.38$
 $-0.594(43.22 - 35.25) = -4.23$

$-0.25(-120 - 46.12 - 6.77) = 43.22$
 $-0.286(120 + 43.22) = -46.68$
 $-0.216(120 + 43.22) = -35.25$

$-0.25(-120 - 46.68 - 8.38) = 43.27$
 $-0.286(120 + 43.27) = -46.83$
 $-0.216(120 + 43.27) = 35.37$
 $-1.052(43.27 - 35.37) = -8.38$
 $-0.594(43.27 - 35.37) = -4.23$

Final moments = FEM + 2XNEC + FEC

Joint	A	B	C	D
Members	AB	BA	CB	DC
FEM	0	0	120	0
2XNEC	2x0	2x43.76	2x43.76	2x-46.83
FEC	43.76	2x0	43.76	0
DEC	-8.82	-8.82	0	-4.98
Final	34.94	78.7	193.1	-98.64

1- Flexibility matrix method is also known as force method
 'compatibility' of method of 'consistent displacements'
 'released structure method' of Base structure method.

1- In this method, basic unknowns are Redundant forces. Hence the analysis has to first identify basic static in of the structure. The no. of Redundant forces is equal to be Static indeterminacy. From the principle of super position displacement at any point is a statically determinate is the sum of the displacements in the basic indeterminate structure due to applied loads & Redundant forces

$$\Delta = [S][P] + [\Delta L]$$

This equation is called as compatibility equation

Flexibility matrix:

If a structure has 'n' no. of loads

The displacement matrix is represented as

$$[S] = \begin{bmatrix} \delta_{11} & \delta_{12} & \delta_{13} & \dots & \delta_{1n} \\ \delta_{21} & \delta_{22} & \delta_{23} & \dots & \delta_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \delta_{n1} & \delta_{n2} & \delta_{n3} & \dots & \delta_{nn} \end{bmatrix}$$

If $n=2$

$$[S] = \begin{bmatrix} \delta_{11} & \delta_{12} \\ \delta_{21} & \delta_{22} \end{bmatrix}_{2 \times 2}$$

Q6 $n=3$

$$[S] = \begin{bmatrix} \delta_{11} & \delta_{12} & \delta_{13} \\ \delta_{21} & \delta_{22} & \delta_{23} \\ \delta_{31} & \delta_{32} & \delta_{33} \end{bmatrix} \quad 3 \times 3$$

Procedure: 1. Determine the degree of static indeterminacy n

check the Redundants

Assign the coordinates to the redundant take directions & draw released beam diagram

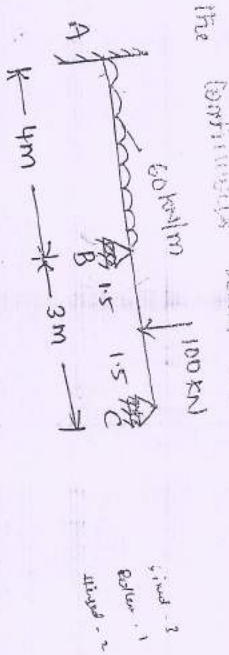
Find the deflection matrix $[\Delta]$

Determine the flexibility matrix by applying a unit force to the coordinates

Applying compatibility conditions to the supports

$$[P] = [S^{-1}] [\Delta - \Delta_L]$$

Analysis The continuous beam spans below are shown



Step 1: Degree of static indeterminacy :-

Number of reaction components = $3 + 1 + 1 = 5$

Number of independent equilibrium equations = 3

Number of independent equilibrium equations = $5 - 3 = 2$

∴ Degree of static indeterminacy = 2

Step 2: Assign the coordinates & draw released beam diagram



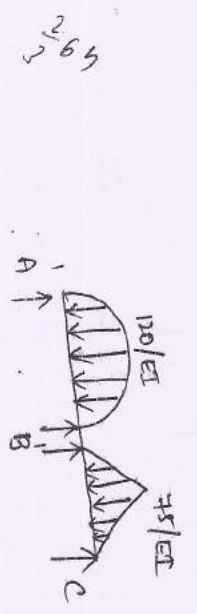
Step 3: Conjugate Beam diagram :-

Free moment diagram in AB = $\frac{wL^3}{8} = \frac{60 \times 4^3}{8} = 120 \text{ kNm}$

in BC = $\frac{wL}{4} = \frac{100 \times 3}{4} = 75 \text{ kNm}$

∴ Conjugate beam = $\frac{M}{EI}$

∴ AB = $\frac{120}{EI}$ and BC = $\frac{75}{EI}$



Step 4: Explanation matrix $[\Delta L]$

ΔL depends on no. of redundant forces. In this case $n=2$

$$\therefore \Delta L = \begin{bmatrix} \Delta L_1 \\ \Delta L_2 \end{bmatrix}$$

$\Delta L_1 = \frac{1}{2}$ [area of conjugate beam at A]

$$= \frac{1}{2} \left[\frac{2}{3} \times 4 \times \frac{120}{EI} \right] = \frac{160}{EI}$$

$\Delta L_2 =$ Rotation at B in A'B' + Rotation at B in B'C

= Shear at B in A'B' + Shear at B in B'C

$$= \frac{1}{2} \left(\frac{2}{3} \times 4 \times \frac{120}{EI} \right) + \frac{1}{2} \left[\frac{1}{2} \times 3 \times \frac{75}{EI} \right]$$

$$= \frac{160}{EI} +$$

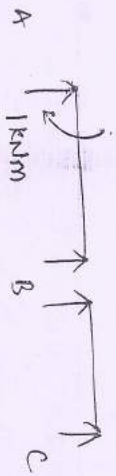
$$\Delta L_2 = \frac{216.25}{EI} \quad \therefore \Delta L = \begin{bmatrix} 160/EI \\ 216.25/EI \end{bmatrix}$$

Step 5: Determine the flexibility matrix by applying unit force to the coordinate.

if $n=2$,

$$f = \begin{bmatrix} f_{11} & f_{12} \\ f_{21} & f_{22} \end{bmatrix}_{2 \times 2}$$

Applying a unit force at the coordinate at points



then released structure & conjugate beam

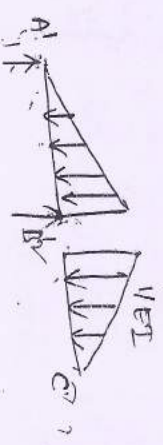
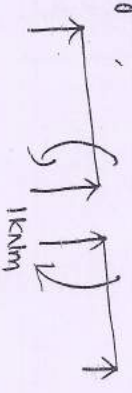


$\delta_{11} = ?$ $\delta_{21} = ?$

$$\delta_{11} = \frac{2}{3} \left(\frac{1}{2} \times 4 \times \frac{1}{EI} \right) = \frac{4}{3EI}$$

$$\delta_{21} = \frac{1}{3} \left(\frac{1}{2} \times 4 \times \frac{1}{EI} \right) = \frac{2}{3EI}$$

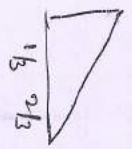
iii) If, a unit load is applied in coordinate direction 2 as shown in figure.



$\delta_{22} = ?$ $\delta_{12} = ?$

$$\delta_{12} = \frac{1}{3} \left(\frac{1}{2} \times 4 \times \frac{1}{EI} \right) = \frac{2}{3EI}$$

and $\delta_{22} = \frac{2}{3} (A_1) + \frac{2}{3} (A_2)$



Step 6 :-

$$\delta_{22} = \frac{4}{3EI} + \frac{3}{3EI}$$

Let redundant forces matrix, if $n=2$ $[P] = \begin{bmatrix} P_1 \\ P_2 \end{bmatrix}$

For consistency conditions, final displacements

$\Delta_1 = 0$ $\Delta_2 = 0$

\therefore The matrix equation is

$$\Delta = [S][P] + [\Delta_L] = 0$$

$$[S][P] = -[\Delta_L]$$

$$\begin{bmatrix} \delta_{11} & \delta_{12} \\ \delta_{21} & \delta_{22} \end{bmatrix} \begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} - \begin{bmatrix} \Delta_{L1} \\ \Delta_{L2} \end{bmatrix}$$

$$\begin{bmatrix} \frac{4}{3EI} & \frac{2}{3EI} \\ \frac{2}{3EI} & \frac{7}{3EI} \end{bmatrix} \begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \begin{bmatrix} -\Delta_{L1} \\ -\Delta_{L2} \end{bmatrix}$$

$$\frac{1}{3EI} \begin{bmatrix} 4 & 2 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \begin{bmatrix} -160/EI \\ -216.5/EI \end{bmatrix}$$

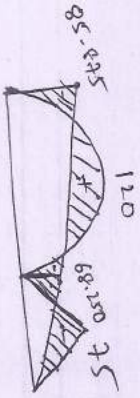
$$\frac{1}{3EI} \begin{bmatrix} 4 & 2 \\ 2 & 7 \end{bmatrix} \begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} -160 \\ -216.5 \end{bmatrix}$$

$$\begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \frac{3}{EI} \begin{bmatrix} 4 & 2 \\ 2 & 7 \end{bmatrix}^{-1} \begin{bmatrix} -160 \\ -216.5 \end{bmatrix}$$

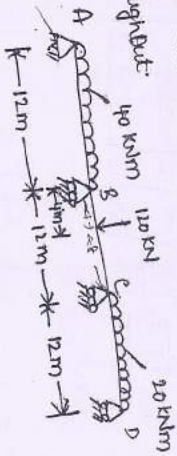
$$\begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \frac{3}{4 \times 7 - 2 \times 2} \begin{bmatrix} 7 & -2 \\ -2 & 4 \end{bmatrix} \begin{bmatrix} -150 \\ -216.5 \end{bmatrix}$$

$$= \frac{1}{8} \begin{bmatrix} -68.7 \\ -54.6 \end{bmatrix} = \begin{bmatrix} -8.5875 \\ -6.8250 \end{bmatrix}$$

Final moments and BMD's are



Step 1: Analyze the continuous beam shown in figure by FEM. Take EI constant throughout.



Step 1: $5 - 3 = 2$
The moment at B and C are taken as redundant forces.

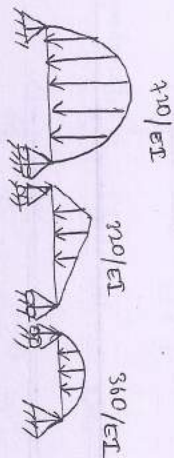
Step 2: Assign the co-ordinates & draw released beam diagram



Free moment diagram in AB = $\frac{40 \times 12^2}{8} = 720$ kNm

Free moment diagram in BC = $\frac{20 \times 4 \times 8}{12} = 320$ kNm

Free moment diagram in CD = $\frac{20 \times 12^2}{8} = 360$ kNm



Step 4: Displacement matrix $[\Delta_L]$

Δ_L depends upon no. of redundant forces. $n = 2$

$$\Delta_L = \begin{bmatrix} \Delta_1 \\ \Delta_2 \end{bmatrix}$$

Δ_1 = Displacement in coordinate direction 1

= Rotation of AB at B + Rotation of BC at B

= shear force in conjugate beam in AB at B + shear force in conjugate beam in BC at B

$$= \frac{1}{2} \left[\frac{2}{3} \times 12 \times \frac{720}{EI} \right] + \frac{1}{2} \left[\frac{12+8}{3} \times \frac{320}{EI} \right]$$

$$= \frac{2880}{EI} + \frac{1066.66}{EI} = \frac{3946.66}{EI}$$

Δ_2 = Displacement in coordinate direction 2

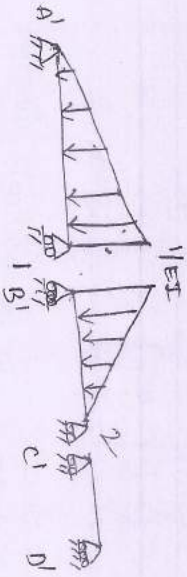
$$= \frac{1}{2} \left[\frac{12+4}{3} \times \frac{320}{EI} \right] + \frac{1}{2} \left[\frac{2}{3} \times 12 \times \frac{360}{EI} \right] = \frac{2293.33}{EI}$$

$$\Delta = \begin{bmatrix} \Delta_1 \\ \Delta_2 \end{bmatrix} = \begin{bmatrix} \frac{3946.67}{EI} \\ \frac{2293.33}{EI} \end{bmatrix}$$

Step 5: ~~Step~~ Determine the flexibility matrix applying unit loads for the co-ordinates

If $n=2$,
$$S = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix}_{2 \times 2}$$

Applying a unit load at the coordinate direction 1

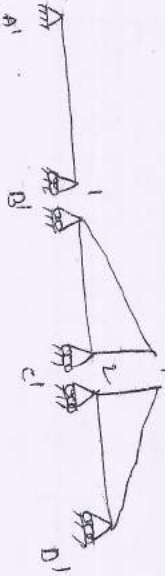
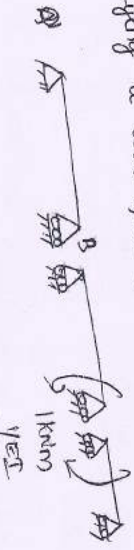


$$\delta_{11} = \frac{2}{3} (A_1) + \frac{2}{3} (A_2)$$

$$= \frac{2}{3} \left(\frac{1}{2} \times 12 \times \frac{1}{EI} \right) + \frac{2}{3} \left(\frac{1}{2} \times 12 \times \frac{1}{EI} \right) = \frac{8}{EI}$$

$$\delta_{21} = \frac{1}{3} \left(\frac{1}{2} \times 12 \times \frac{1}{EI} \right) = \frac{2}{EI}$$

Applying a unit load at the coordinate direction 2



$$S_{22} = \frac{1}{3} \left(\frac{1}{2} \times 12 \times \frac{1}{EI} \right) = \frac{2}{EI}$$

$$S_{22} = \frac{2}{3} \left(\frac{1}{2} \times 12 \times \frac{1}{EI} \right) + \frac{2}{3} \left(\frac{1}{2} \times 12 \times \frac{1}{EI} \right)$$

$$= \frac{8}{EI}$$

Step 6:

$$n=2, P = \begin{bmatrix} P_1 \\ P_2 \end{bmatrix}$$

$$\Delta = \begin{bmatrix} \Delta_1 \\ \Delta_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

\therefore The matrix equation is

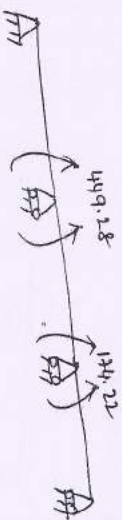
$$\Delta = [S][P] + [\Delta_L]$$

$$[8][P] = [\Delta] - [\Delta_L]$$

$$\begin{bmatrix} \frac{8}{EI} & \frac{2}{EI} \\ \frac{2}{EI} & \frac{8}{EI} \end{bmatrix} \begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} - \begin{bmatrix} \frac{3946.67}{EI} \\ \frac{2293.33}{EI} \end{bmatrix}$$

$$\begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = - \begin{bmatrix} 8 & 2 \\ 2 & 8 \end{bmatrix}^{-1} \begin{bmatrix} 3946.67 \\ 2293.33 \end{bmatrix}$$

$$= - \frac{1}{64-4} \begin{bmatrix} 8 & -2 \\ -2 & 8 \end{bmatrix} \begin{bmatrix} 3946.67 \\ 2293.33 \end{bmatrix} = \begin{bmatrix} -449 \\ -144 \end{bmatrix}$$





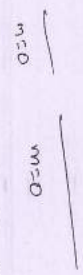
B' sink by 10mm

Q1
D.S = 5 - 3 = 2

Step 2
Release beam diagram



Step 3
Conjugate Beam diagram



Step 4
Displacement matrix $[A]$

$$8 = \begin{bmatrix} \delta_{11} & \delta_{12} \\ \delta_{21} & \delta_{22} \end{bmatrix}$$

$n=2$

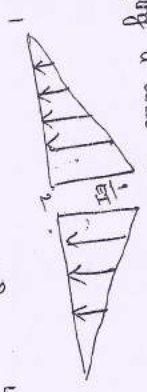
applying a unit force to the point 1



$$\delta_{11} = \frac{2}{3} \left(\frac{1}{2} \times 8 \times \frac{1}{EI} \right) = \frac{8}{3EI}$$

$$\delta_{21} = \frac{1}{3} \left(\frac{1}{2} \times 8 \times \frac{1}{EI} \right) = \frac{4}{3EI}$$

applying a unit force to the point 2



$$\delta_{12} = \frac{1}{3} \left[\frac{1}{2} \times 8 \times \frac{1}{EI} \right] = \frac{4}{3EI}$$

$$\delta_{22} = \frac{2}{3} \left[\frac{1}{2} \times 8 \times \frac{1}{EI} \right] + \frac{2}{3} \left[\frac{1}{2} \times 8 \times \frac{1}{EI} \right] = \frac{14}{3EI}$$

$$[P] = [Q] [A^{-1}]$$

$$\begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \begin{bmatrix} \delta_{11} & \delta_{12} \\ \delta_{21} & \delta_{22} \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 8/3EI & 4/3EI \\ 4/3EI & 14/3EI \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 8/3 & 4/3 \\ 4/3 & 14/3 \end{bmatrix}^{-1}$$

$$= \frac{1}{2.5 \times 10^3} \begin{bmatrix} 1.25 \times 10^3 & -0.5 \times 10^3 \\ 0.5 \times 10^3 & 1.25 \times 10^3 \end{bmatrix}$$

$$M_A = -1.25 \times 10^3 \text{ kN-m}$$

$$M_B = 2.5 \times 10^3 \text{ kN-m}$$

In this method, the basic unknowns are to do in the analysis are the rotations (settlement values). Then by slope deflection method equations we can find Redundant (ie moments). In this method the stiffness matrix depend on

$$K = \begin{bmatrix} k_{11} & k_{12} & \dots & k_{1n} \\ k_{21} & \dots & \dots & \dots \\ \vdots & \dots & \dots & \dots \\ k_{n1} & \dots & \dots & k_{nn} \end{bmatrix}$$

By using compatibility conditions find moments at the supports will be obtained.

$$[K][\theta] = [\Delta] - [\Delta_L]$$

$$\theta = [K^{-1}][\Delta] - [\Delta_L]$$

where $[K]$ - stiffness matrix

$$[\theta] = \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_n \end{bmatrix} - \theta = \text{rotation contribution value supports}$$

$[\Delta]$ = settlement matrix

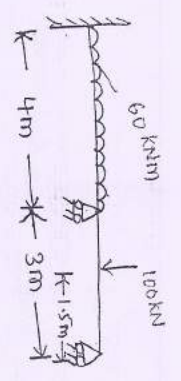
$[\Delta_L]$ = fixed end moment matrix

Procedure:

- 1) $D_R = ?$
Degree of kinematic indeterminacy of structure
- 2) Assign co-ordinate values
- 3) Draw fully restrained structure
- 4) Find out fixed end moment
- 5) Determine Δ_L
- 6) Determine stiffness matrix by giving unit displacement (rotation) to the restrained structure.
- 7) Form eqn & solve the stiffness eqns
to get the displacement (rotation) (rotation values) at various co-ordinate points.
By using slope deflection method eqn fixed moments will be determined.

$$[\theta] = [k]^{-1} [\Delta] - [\Delta_L]$$

* Analyse the continuous beam shown as given by slope deflection method



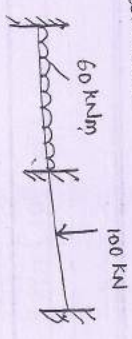
Sol:

1) $D_R = 5 - 3 = 2$

2) co-ordinates selection



3) Fully restrained structure



4) Fixed end moments

$$M_{FAB} = -\frac{60 \times 4^2}{12} = -80 \text{ kNm}$$

$$M_{FBA} = 80 \text{ kNm}$$

$$M_{FBC} = -\frac{100 \times 3}{8}$$

$$M_{FCB} = 37.5 \text{ kNm}$$

5) $\Delta_L = \begin{bmatrix} \Delta_1 \\ \Delta_2 \end{bmatrix}$

$$\Delta_1 = M_{FBA} + M_{FBC} = 80 - 37.5 = 42.5$$

$$\Delta_2 = M_{FCB} = 37.5$$

$$\therefore \Delta_L = \begin{bmatrix} 42.5 \\ 37.5 \end{bmatrix}$$

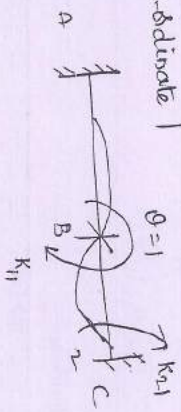
For $\theta = 2$

$$[K] = \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix}$$

→ To determine stiffness matrix unit displacement is applied at the coordinate to restrained structure

→ We use slope-deflection eqn at the co-ordinates

unit displacement
→ at co-ordinate 1



$$\theta_B = 1$$

$$\theta_A = 0$$

$$K_{11} = \frac{2EI}{L} (2\theta_B + \theta_A) + \frac{2EI}{L} (2\theta_B + \theta_C)$$

$$= \frac{2EI}{L} (2(1)) + \frac{2EI}{L} (2(1))$$

$$= EI + \frac{4}{3} EI = \frac{7EI}{3}$$

$$K_{21} = \frac{2EI}{L} (2\theta_C + \theta_B) = \frac{2EI}{L} (0 + 1) = \frac{2EI}{L}$$

→ unit displacement at co-ordinate 2



$$K_{22} = \frac{2EI}{L} (2\theta_C + \theta_B) = \frac{2EI}{L} (2) = \frac{4EI}{L}$$

$$K_{12} = \frac{2EI}{L} (2\theta_B + \theta_C) = \frac{2EI}{L}$$

$$[D] = [K]^{-1} [\Delta] - \Delta_0$$

$$= \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 42.5 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{7}{13} EI & \frac{2}{13} EI \\ \frac{2}{13} EI & \frac{4}{13} EI \end{bmatrix}^{-1} \begin{bmatrix} 42.5 \\ 37.5 \end{bmatrix}$$

$$= -\frac{1}{EI} \begin{bmatrix} \frac{7}{13} & \frac{2}{13} \\ \frac{2}{13} & \frac{4}{13} \end{bmatrix} \begin{bmatrix} 42.5 \\ 37.5 \end{bmatrix}$$

$$\begin{bmatrix} \theta_B \\ \theta_C \end{bmatrix} = - \begin{bmatrix} 11.875 \\ 22.187 \end{bmatrix} \frac{1}{EI}$$

$$\theta_B = -11.875/EI \quad \theta_C = -22.187/EI$$

(b) Final moments

$$M_{AB} = M_{FAB} + \frac{2EI}{L} (2\theta_A + \theta_B) = -80 + \frac{2EI}{L} (2(0) - \frac{11.875}{EI})$$

$$= -85.93 \text{ kNm}$$

$$M_{BA} = M_{FBA} + \frac{2EI}{L} (2\theta_B + \theta_A) = 80 + \frac{2EI}{L} (2(-\frac{11.875}{EI}) + 0) = 6$$

$$M_{BC} = M_{FBC} + \frac{2EI}{L} (2\theta_B + \theta_C) = -37.5 + \frac{2EI}{L} (2(-\frac{11.875}{EI}) - \frac{22.187}{EI})$$

$$= M_B = -68.125 \text{ kN-m}$$

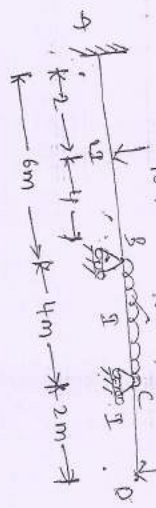
$$M_{CB} = M_{FCB} + \frac{2EI}{L} (2\theta_C + \theta_B)$$

$$= 37.5 + \frac{2EI}{L} (2(-\frac{22.187}{EI}) - \frac{11.875}{EI}) = 37.5 - 23.5 = 14$$

$$\therefore M_{CB} = 0$$

$$\therefore M_C = 0$$

Stiffness matrix method



Step-1: 5-3=2,

Overhanging portion is a determinate portion,

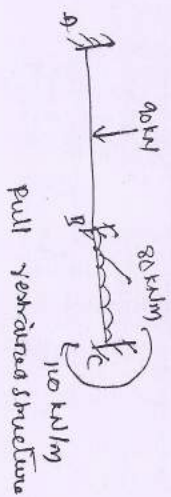
at X taken as cantilever moment, find moment at C



Step-2: Released beam Diagram



coordinates selected



Step-3: Pinned end moments

$$M_{PAB} = \frac{-90 \times 2 \times 4^2}{6} = -80 \text{ kNm}$$

$$M_{PBC} = \frac{90 \times 2^2 \times 4}{6} = 40 \text{ kNm}$$

$$M_{PBC} = \frac{-80 \times 4}{12} = -106.67 \text{ kNm}$$

$$M_{FCB} = 106.67 \text{ kNm}$$

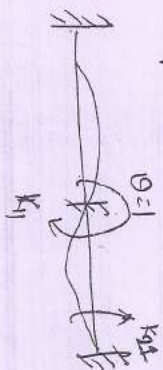
$$[A] = \begin{bmatrix} M_{PAB} & M_{PBC} \\ M_{FCB} & M_{FCB} \end{bmatrix} = \begin{bmatrix} -80 & 40 \\ 106.67 & 106.67 \end{bmatrix}$$

6) for n=2,

$$[K] = \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix}$$

Stiffness matrix, K,

a) unit matrix displacement in coordinate direction 1



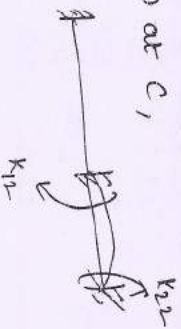
K11 = moment required to rotate BA and BC by 1

$$= \frac{2EI}{L} [2\theta_B + \theta_A - 0] + \frac{2EI}{L} (2\theta_B + \theta_C - 0)$$

$$= \frac{2EI(2I)}{6} [2 \times 1 + 0] + \frac{2EI}{4} [2 \times 1 + 0]$$

$$= \frac{8EI}{6} + EI = \frac{7}{3} EI$$

b) unit rotation at C,



$$K_{21} = \frac{2EI}{4} [2\theta_B + \theta_C + 0] = 0.5EI$$

$$K_{22} = \frac{2EI}{4} [2\theta_C + 0] = EI$$

The stiffness matrix $K_2 = \begin{bmatrix} \frac{4EI}{L} & 0 \\ 0 & \frac{3EI}{L} \end{bmatrix}$

The stiffness matrix equation is

$$[K][\theta] = [A-A]$$

$$\therefore \Delta = \begin{bmatrix} 0 \\ 120 \end{bmatrix}$$

$$\begin{bmatrix} \frac{4EI}{3} & 0.5EI \\ 0.5EI & EI \end{bmatrix} \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 0 & -(66.67) \\ 120 & 106.67 \end{bmatrix}$$



$$\frac{EI}{3} \begin{bmatrix} 4 & 1.5 \\ 1.5 & 3 \end{bmatrix} \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} = \begin{bmatrix} 66.67 \\ 13.33 \end{bmatrix}$$

$$\begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} = \frac{3}{EI} \begin{bmatrix} 4 & 1.5 \\ 1.5 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 66.67 \\ 13.33 \end{bmatrix}$$

$$= \frac{3}{EI} \left(\frac{1}{4 \times 3 - 1.5^2} \right) \begin{bmatrix} 3 & -1.5 \\ -1.5 & 4 \end{bmatrix} \begin{bmatrix} 66.67 \\ 13.33 \end{bmatrix}$$

$$= \frac{3}{EI} \times \frac{1}{18.75} \begin{bmatrix} 140.015 \\ -66.95 \end{bmatrix}$$

$$= \frac{1}{EI} \begin{bmatrix} 28.802 \\ -1.017 \end{bmatrix}$$

$$\theta_B = \frac{28.802}{EI} \quad \& \quad \theta_C = \frac{-1.017}{EI}$$

From slope deflection equation

$$M_{AB} = M_{FAB} + \frac{2EI}{L} (2\theta_A + \theta_B - 0)$$

$$= -60.80 \text{ kNm}$$

$$M_{B9} = 40 + \frac{2E(2\theta)}{6} \left(0 + 2 \times \frac{28.802}{EI} - 0 \right) = 28.403 \text{ kNm}$$

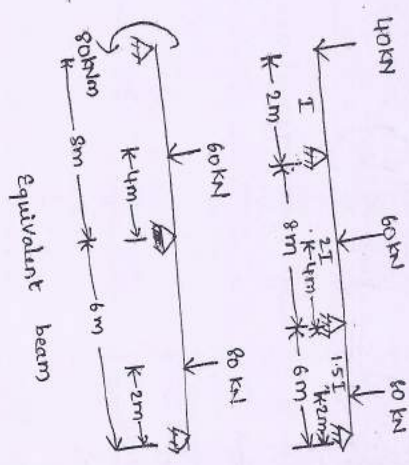
$$M_{BC} = -106.67 + \frac{2EI}{4} (2\theta_B + \theta_C - 0)$$

$$= -106.67 + \frac{2EI}{4} \left(\frac{2 \times 28.802}{EI} - \frac{1091}{EI} \right) = -98.403 \text{ kNm}$$

$$M_{0B} = -106.67 + \frac{2EI}{4} (\theta_B + 2\theta_C - 0)$$

$$= -106.67 + \frac{2EI}{4} \left(\frac{28.802}{EI} - \frac{2 \times 1.017}{EI} \right) = 120 \text{ kNm}$$

* Analyze the continuous beam shown in figure by displacement





fully restrained structure

Final force vector $[\Delta] = \begin{bmatrix} -40 \\ 0 \\ 0 \end{bmatrix}$

fixed end moments:-

$M_{FBC} = -\frac{60 \times 8}{8} = -60 \text{ kNm}$

$M_{FCB} = 60 \text{ kNm}$

$M_{FCD} = -\frac{80 \times 4 \times 2}{6} = -35.55 \text{ kNm}$

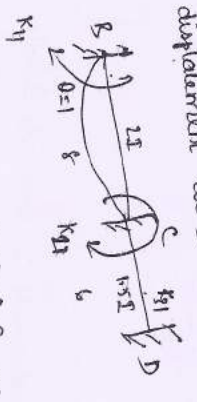
$M_{FDC} = \frac{80 \times 4 \times 2}{6} = 35.55 \text{ kNm}$

Displacement matrix

$\therefore [A] = \begin{bmatrix} \Delta_1 \\ \Delta_2 \\ \Delta_3 \end{bmatrix} = \begin{bmatrix} M_{FBC} & M_{FCB} & M_{FCD} \\ M_{FCB} & M_{FCB} & M_{FCD} \\ M_{FDC} & M_{FDC} & M_{FDC} \end{bmatrix} = \begin{bmatrix} -60 & 60 & -35.55 \\ 60 & -35.55 & 35.55 \\ 35.55 & 35.55 & 35.55 \end{bmatrix}$

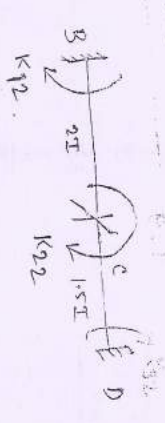
stiffness matrix:- $n=3, k = \begin{bmatrix} k_{11} & k_{12} & k_{13} \\ k_{21} & k_{22} & k_{23} \\ k_{31} & k_{32} & k_{33} \end{bmatrix}$

(a) unit displacement at B



$\therefore K_{11} = K_{BC} = \frac{2E(2I)}{8} (2 \times 20 + 0 - 0) = EI$

$\therefore K_{31} = K_{CB} = \frac{2E(2I)}{8} (20 + 0 - 0) = 0.5 EI$

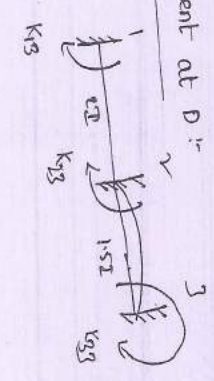


$K_{12} = \frac{2E(2I)}{8} = 0.5 EI$

$K_{22} = \frac{2E(2I)}{8} (2) + \frac{2E(0.5I)}{8} = 2EI$

$K_{32} = \frac{2E(0.5I)}{6} = 0.5 EI$

(c) unit displacement at D:-



$K_{23} = \frac{2E(0.5I)}{6} = 0.5 EI$

stiffness matrix equation 'K'

$[K][\theta] = [A] - [\Delta]$

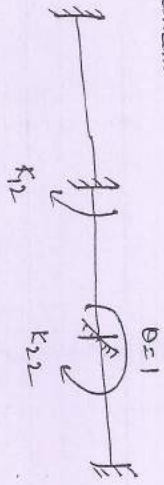
$EI \begin{bmatrix} 1 & 0.5 & 0 \\ 0.5 & 2 & 0.5 \\ 0 & 0.5 & 1 \end{bmatrix} \begin{bmatrix} \theta_B \\ \theta_C \\ \theta_D \end{bmatrix} = \begin{bmatrix} -80 + 60 \\ 0 - 24 + 45 \\ -71.11 \end{bmatrix}$

$\begin{bmatrix} \theta_B \\ \theta_C \\ \theta_D \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} 1 & 0.5 & 0 \\ 0.5 & 2 & 0.5 \\ 0 & 0.5 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -20 \\ -24 + 45 \\ -71.11 \end{bmatrix}$

$$K_{11} = \frac{4E(2I)}{3} + \frac{4E(2.5I)}{4} = 5.167 EI$$

$$K_{12} = \frac{2EI}{L} (2\theta_C + \theta_B) = \frac{2E(2.5I)}{4} = 1.25 EI$$

(B) unit displacement in Δ direction



$$K_{12} = \frac{2EI}{L} (2\theta_B + \theta_C) = \frac{2E(2.5I)}{4} = 1.25 EI$$

$$K_{22} = \frac{2EI}{L} (2\theta_C + \theta_B) + \frac{2EI}{L} (2\theta_C + \theta_B)$$

$$= \frac{2E(2.5I)}{4} (2) + \frac{2E(2.5I)}{4} (2) \\ = 5EI$$

\therefore Therefore stiffness equation is given by

$$[K] \{\theta\} = [F] - [F_0]$$

$$EI \begin{bmatrix} 5.167 & 1.25 \\ 1.25 & 5 \end{bmatrix} \begin{bmatrix} \theta_B \\ \theta_C \end{bmatrix} = \begin{bmatrix} 0 & -(-23.75) \\ 0 & -56.25 \end{bmatrix}$$

$$\begin{bmatrix} \theta_B \\ \theta_C \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} 5.167 & 1.25 \\ 1.25 & 5 \end{bmatrix}^{-1} \begin{bmatrix} 23.75 \\ -56.25 \end{bmatrix}$$

$$\begin{bmatrix} \theta_B \\ \theta_C \end{bmatrix} = \frac{1}{EI} \begin{bmatrix} 5.167 & 1.25 \\ 1.25 & 5 \end{bmatrix}^{-1} \begin{bmatrix} 23.75 \\ -56.25 \end{bmatrix} \\ = \frac{1}{EI} \begin{bmatrix} 7.79 \\ -13.198 \end{bmatrix}$$

$$\theta_B = \frac{7.79}{EI} \quad \text{and} \quad \theta_C = \frac{-13.198}{EI}$$

$$\therefore M_{AB} = M_{FAB} + \frac{2EI}{L} (2\theta_A + \theta_B)$$

$$= -80 + \frac{2E(22)}{3} \left(0 + \frac{7.79}{EI} \right) = -69.613 \text{ kNm}$$

$$M_{BA} = M_{FBA} + \frac{2EI}{L} (2\theta_B + \theta_A)$$

$$= 80 + \frac{2E(22)}{3} \left(0 + 2 \times \frac{7.79}{EI} \right) = -59.229 \text{ kNm}$$

$$M_{BC} = M_{FBC} + \frac{2EI}{L} (2\theta_B + \theta_C)$$

$$= 56.25 + \frac{2E(22)}{4} \left(\frac{2 \times 7.79}{EI} - \frac{13.198}{EI} \right) = 5$$

$$M_{CB} = M_{FCB} + \frac{2EI}{L} (2\theta_C + \theta_B)$$

$$= 56.25 + \frac{2E(22)}{4} \left(\frac{2 \times -13.198}{EI} + \frac{7.79}{EI} \right)$$

$$= 33 \text{ kNm}$$

